

M54644BL

BI-DIRECTIONAL MOTOR DRIVER

DESCRIPTION

The M54644BL is a semiconductor IC capable of directly driving a smallsize bi-directional motor for forward/reverse rotation.

FEATURES

- Wide operating voltage range ($V_{cc} = 4V$ to $16V$)
- Low output saturation voltage (large voltage across motor)
- Built-in clamp diode
- Large output current drive (I_o (max) = $\pm 2A$)
- With brake function
- Built-in thermal protector circuit

APPLICATION

Commercial-use equipment, audio such as tape recorder or radio cassette recorder.

FUNCTIONAL DESCRIPTION

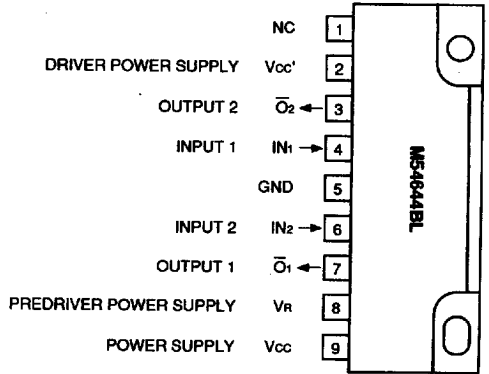
The M54644BL consists of input circuits, a control circuit, output circuits, a thermal protector circuit and a constant current circuit.

As given in the logic truth table, the basic operations include determination of status of outputs \bar{O}_1 and \bar{O}_2 in correspondence with inputs IN_1 and IN_2 , and four operational controls of forward rotation, reverse rotation, brake and stop of a motor.

Normally, the V_R pin is a power supply for predrive but can be used as a pin for controlling the level of "H" output voltage (application example 4).

The IC is provided with a built-in thermal protector circuit. If the chip temperature (junction temperature) is $125^\circ C$ or over, the circuit operation is stopped to protect the IC. For normal use, the power dissipation should not be exceeded.

PIN CONFIGURATION (TOP VIEW)



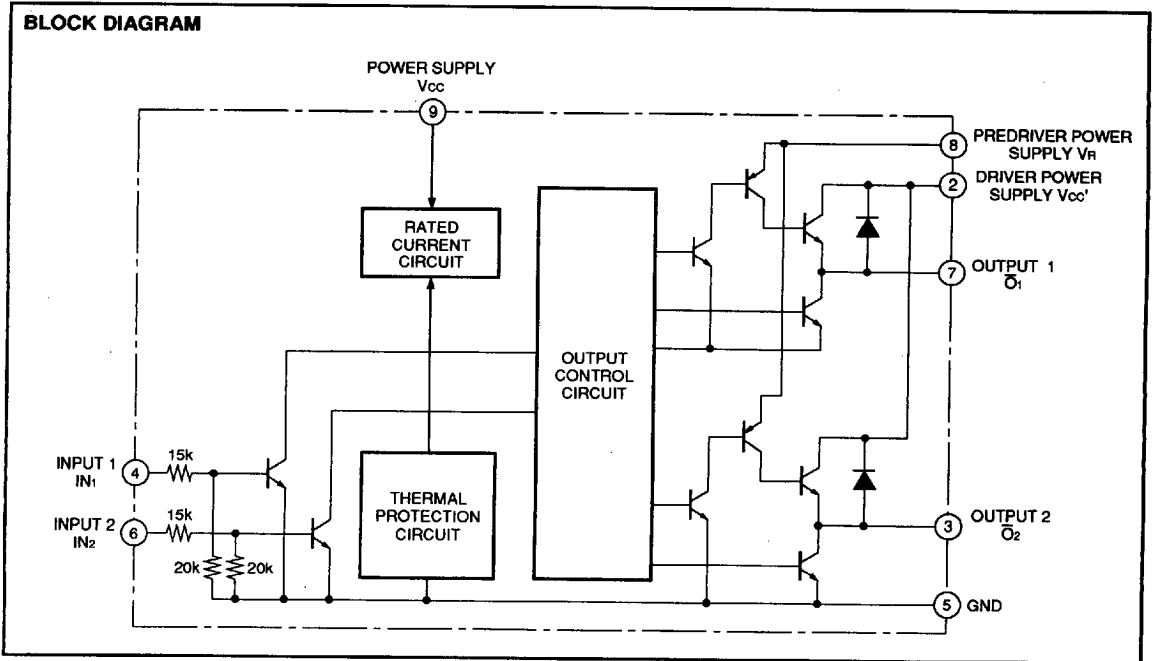
Outline 9P9

NC : NO CONNECTION

LOGIC TRUTH TABLE

| INPUT | | OUTPUT | | NOTE |
|--------|--------|-------------|-------------|------------|
| IN_1 | IN_2 | \bar{O}_1 | \bar{O}_2 | |
| L | L | OFF | OFF | Open |
| H | L | H | L | ex.Forward |
| L | H | L | H | ex.Reverse |
| H | H | L | L | Braking |

BLOCK DIAGRAM



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BI-DIRECTIONAL MOTOR DRIVER

ABSOLUTE MAXIMUM RATINGS (Ta=25°C, unless otherwise noted)

| Symbol | Parameter | Conditions | Ratings | Unit |
|----------|---------------------------|---|------------------|------|
| Vcc | Supply voltage | | -0.5 to +16 | V |
| Vcc' | Driver supply voltage | With an external heat sink (30cm ² ×1.5mm) | -0.5 to +24 | V |
| VR | Control voltage | | -0.5 to +24 | V |
| Vi | Input voltage | Vi < Vcc | 0 to 7 | V |
| Vo | Output voltage | | -0.5 to Vcc'+2.5 | V |
| Io (max) | Peak output current | top ≤ 100ms: Repetitive cycle 5sec max | ±2 | A |
| Io | Continuous output current | With an external heat sink (30cm ² ×1.5mm) | ±600 | mA |
| Pd | Power dissipation | | 1.54 | W |
| Topr | Operating temperature | | -10 to +75 | °C |
| Tstg | Storage temperature | | -55 to +125 | °C |

RECOMMENDED OPERATING CONDITIONS (Ta=25°C, unless otherwise noted)

| Symbol | Parameter | Test conditions | Limits | | | Unit |
|--------|------------------------------|---|--------|------|------|------|
| | | | Min. | Typ. | Max. | |
| Vcc | Supply voltage | | 4 | 5 | 16 | V |
| Io | Continuous output current | With an external heat sink (30cm ² ×1.5mm) | | | ±500 | mA |
| VIH | "H" Input voltage | | 2.0 | | Vcc | V |
| VIL | "L" Input voltage | | 0 | | 0.4 | V |
| tB | Motor braking interval | | 10 | 100 | | ms |
| Tshut | Thermal shutdown temperature | | 125 | 150 | | °C |
| VR | Control voltage | | 0 | | Vcc' | V |

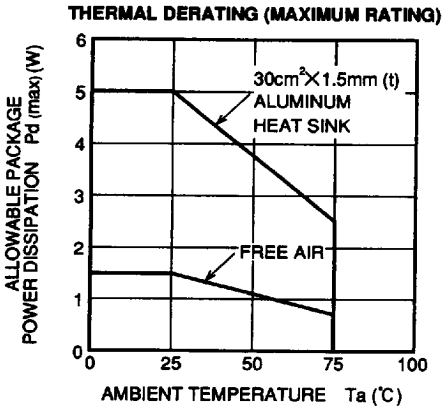
ELECTRICAL CHARACTERISTICS (Ta=25°C, unless otherwise noted)

| Symbol | Parameter | Test conditions | Limits | | | Unit |
|-----------|-------------------------------|---|--------|-------------|------------|------|
| | | | Min. | Typ. | Max. | |
| Io (leak) | Output leak current | Vcc=16V, Vcc'-VR=24V Vi1=Vi2=0.4V, Vo=0V or 24V | | | ±100 | μA |
| VOH | "H" Output saturation voltage | Vcc=Vcc'-VR=16V Io=-500mA (Vi1=0.4V Vi2=2.0V or (Vi1=2.0V Vi2=0.4V | 14.5 | 15.2 | | V |
| VOL | "L" Output saturation voltage | Vcc=Vcc' =VR=16V (Vi1=0.4V Vi2=2.0V or (Vi1=2.0V Vi2=0.4V | | 0.1 0.18 | 0.4 1.4 | V |
| Ii | Input current | Vcc=Vcc'-VR=16V Vi=2.0V | 50 | 90 | 120 | μA |
| Icc | Supply current | Vcc=16V, Vcc'-VR=16V Vi1=Vi2=0V Output open | | 2.6 | 5 | mA |
| | | Vcc=16V, Vcc'-VR=16V Output open (Vi1=0.4V Vi2=2.0V or (Vi1=2.0V Vi2=0.4V | | 8 | 15 | |
| | | Vcc=16V, Vi1=Vi2=2.0V Vcc'-VR=16V Output open | | 14 | 25 | |
| IR | Control pin input current | Vcc=16V, Vcc'-VR=16V (Vi1=0.4V Vi2=2.0V or (Vi1=2.0V Vi2=0.4V | | 0.2 | 1.0 | mA |

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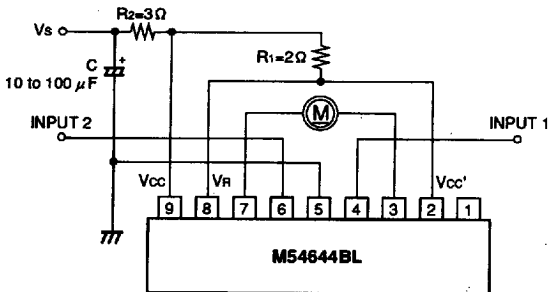


TYPICAL CHARACTERISTICS

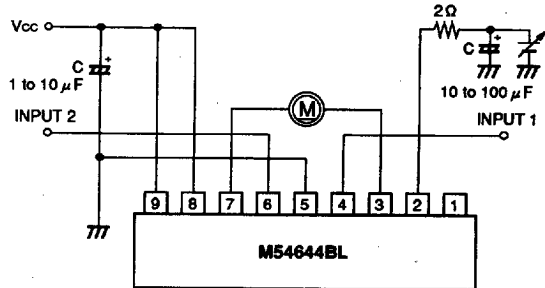


APPLICATION EXAMPLES

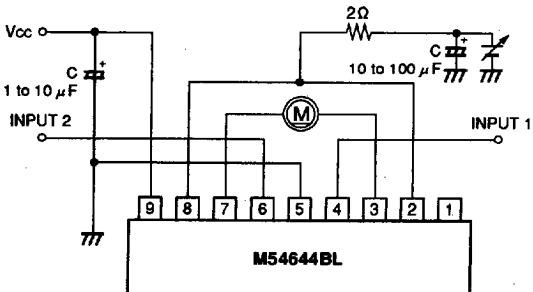
1) Motor speed control by V_{cc} , V_{cc}' and V_R



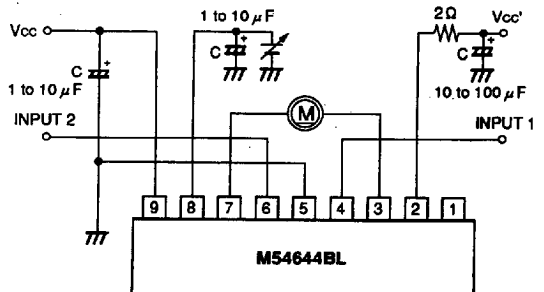
2) Motor speed control by the V_{cc}'



3) Motor speed control by the V_R and V_{cc}'



4) Motor speed control by the V_R



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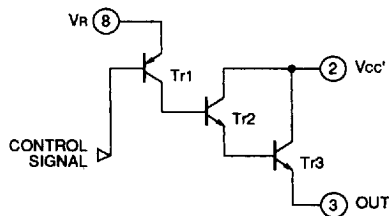
PRECAUTIONS FOR APPLICATION

1. Output voltage control method

The output control circuit by pin No.8 is as shown at right. Voltage about 1.4V lower than that at pin No.8 is output ("H" side).

$$V_{OH} \doteq V_R - V_{sat}(Tr1) - V_{BE}(Tr2) - V_{BE}(Tr3)$$

However, when V_R is 1.4V or below, $V_{OH}=0V$.



2. Allowable power dissipation

The allowable power dissipation (P_d) of IC is calculated as follows:

$$P_d \doteq V_{cc} \times I_{cc} + I_o \times \{(V_{cc}' - V_{OH}) + V_{OL}\}$$

In design, do not exceed the maximum allowable power dissipation indicated in the thermal derating diagram.

Remember that if rush current flows repeatedly, the power dissipation becomes small.

3. Thermal shut-down

A thermal breaker is built in the circuit to prevent thermal destruction when overpower is applied.

The function works when the IC chip temperature goes to 150°C (min. 125°C), placing the IC in the output OPEN mode. When the temperature goes down to 100°C (max. 125°C), the function is reset.

●The thermal protection of the IC may not work depending on an abnormal condition (such as oscillation, low supply voltage or output short). When using the function, check its operation in the packaged state.

If the motor has a large counter electromotive force at a braking time, etc., the internal parasitic Di may malfunction.

If fly-back current of 1A or more flows, put a shottkey Di between the output and the GND.

Remember that the IC has an about 10 μ s delay in output switching for high-speed applications such as PWM.

4. Notice

As far as motor control and driver IC's are concerned, some possibilities are considered for these IC's to cause such unexpected cases as fire or smoke if they are used beyond its ratings in datasheet or used, even transiently, under the overload conditions. So your action will be highly appreciated to fully look into the rating limits and the using conditions before you use these IC's.

And if these IC's are to be used under the conditions out of our specifications, please never fail to give us a contact as to under what conditions they are used.

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