

DS90LV028AQ

Automotive LVDS Dual Differential Line Receiver

General Description

The DS90LV028AQ is a dual CMOS differential line receiver designed for applications requiring ultra low power dissipation, low noise and high data rates. The device is designed to support data rates in excess of 400 Mbps (200 MHz) utilizing Low Voltage Differential Signaling (LVDS) technology.

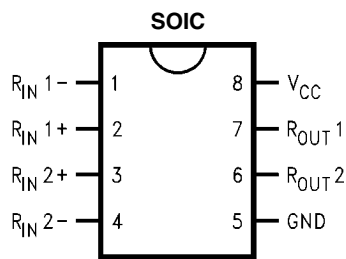
The DS90LV028AQ accepts low voltage (350 mV typical) differential input signals and translates them to 3V CMOS output levels. The DS90LV028AQ has a flow-through design for easy PCB layout.

The DS90LV028AQ and companion LVDS line driver DS90LV027AQ provide a new alternative to high power PECL/ECL devices for high speed point-to-point interface applications.

Features

- AECQ-100 Grade 3
- -40°C to +85°C operating temperature range
- >400 Mbps (200 MHz) switching rates
- 50 ps differential skew (typical)
- 0.1 ns channel-to-channel skew (typical)
- 2.5 ns maximum propagation delay
- 3.3V power supply design
- Flow-through pinout
- Power down high impedance on LVDS inputs
- Low Power design (18mW @ 3.3V static)
- LVDS inputs accept LVDS/CML/LVPECL signals
- Conforms to ANSI/TIA/EIA-644 Standard
- Available in SOIC package

Connection Diagram

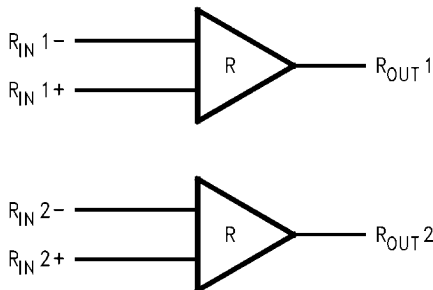


Order Number DS90LV028AQMA³⁰⁰⁶⁴¹⁰¹
See NS Package Number M08A

Truth Table

INPUTS	OUTPUT
$[R_{IN+}] - [R_{IN-}]$	R_{OUT}
$V_{ID} \geq 0.1V$	H
$V_{ID} \leq -0.1V$	L

Functional Diagram



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Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

Supply Voltage (V_{CC})	-0.3V to +4V
Input Voltage (R_{IN+} , R_{IN-})	-0.3V to +3.9V
Output Voltage (R_{OUT})	-0.3V to $V_{CC} + 0.3V$
Maximum Package Power Dissipation @ +25°C	
M Package	541 mW
Derate M Package	6.8 mW/°C above +25°C
Thermal Resistance, θ_{JA} (0 airflow)	148.0°C/W
Thermal Resistance, θ_{JC} (0 airflow)	41.0°C/W
Storage Temperature Range	-65°C to +150°C

Lead Temperature Range Soldering (4 sec.)	+260°C
Maximum Junction Temperature	+105°C
ESD Rating	
HBM 1.5 kΩ, 100 pF	≥ 8 kV
EIAJ 0Ω, 200 pF	≥ 250 V
CDM	≥ 1250 V

Recommended Operating Conditions

	Min	Typ	Max	Units
Supply Voltage (V_{CC})	+3.0	+3.3	+3.6	V
Receiver Input Voltage	GND		3.0	V
Operating Free Air Temperature (T_A) (Note 13)	-40	25	+85	°C

Electrical Characteristics

Over Supply Voltage and Operating Temperature ranges, unless otherwise specified. (Notes 2, 3)

Symbol	Parameter	Conditions	Pin	Min	Typ	Max	Units	
V_{TH}	Differential Input High Threshold	$V_{CM} = +1.2V, 0V, 3V$ (Note 11)	R_{IN+}			+100	mV	
V_{TL}	Differential Input Low Threshold		R_{IN-}	-100			mV	
I_{IN}	Input Current	$V_{IN} = +2.8V$						
		$V_{CC} = 3.6V$ or $0V$						
		$V_{IN} = 0V$						
		$V_{IN} = +3.6V$	$V_{CC} = 0V$					
V_{OH}	Output High Voltage	$I_{OH} = -0.4$ mA, $V_{ID} = +200$ mV	R_{OUT}					
		$I_{OH} = -0.4$ mA, Inputs terminated						
		$I_{OH} = -0.4$ mA, Inputs shorted						
V_{OL}	Output Low Voltage	$I_{OL} = 2$ mA, $V_{ID} = -200$ mV				0.3	0.5	V
I_{OS}	Output Short Circuit Current	$V_{OUT} = 0V$ (Note 4)		-15	-50	-100	mA	
V_{CL}	Input Clamp Voltage	$I_{CL} = -18$ mA		-1.5	-0.8		V	
I_{CC}	No Load Supply Current	Inputs Open	V_{CC}		5.4	9	mA	

Switching Characteristics

$V_{CC} = +3.3V \pm 10\%$, $T_A = -40^\circ C$ to $+85^\circ C$ (Notes 5, 6)

Symbol	Parameter	Conditions	Min	Typ	Max	Units	
t_{PHLD}	Differential Propagation Delay High to Low	$C_L = 15$ pF $V_{ID} = 200$ mV (Figure 1 and Figure 2)	1.0	1.6	2.5	ns	
t_{PLHD}	Differential Propagation Delay Low to High		1.0	1.7	2.5	ns	
t_{SKD1}	Differential Pulse Skew $ t_{PHLD} - t_{PLHD} $ (Note 7)		0	50	650	ps	
t_{SKD2}	Differential Channel-to-Channel Skew-same device (Note 8)		0	0.1	0.5	ns	
t_{SKD3}	Differential Part to Part Skew (Note 9)		0		1.0	ns	
t_{SKD4}	Differential Part to Part Skew (Note 10)		0		1.5	ns	
t_{TLH}	Rise Time			325	800	ps	
t_{THL}	Fall Time			225	800	ps	
f_{MAX}	Maximum Operating Frequency (Note 12)				250		MHz

Note 1: "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. They are not meant to imply that the devices should be operated at these limits. The table of "Electrical Characteristics" specifies conditions of device operation.

Note 2: Current into device pins is defined as positive. Current out of device pins is defined as negative. All voltages are referenced to ground unless otherwise specified (such as V_{ID}).

Note 3: All typicals are given for: $V_{CC} = +3.3V$ and $T_A = +25^\circ C$.

Note 4: Output short circuit current (I_{OS}) is specified as magnitude only, minus sign indicates direction only. Only one output should be shorted at a time, do not exceed maximum junction temperature specification.

Note 5: C_L includes probe and jig capacitance.

Note 6: Generator waveform for all tests unless otherwise specified: $f = 1 \text{ MHz}$, $Z_O = 50\Omega$, t_r and t_f (0% to 100%) $\leq 3 \text{ ns}$ for R_{IN} .

Note 7: t_{SKD1} is the magnitude difference in differential propagation delay time between the positive-going-edge and the negative-going-edge of the same channel.

Note 8: t_{SKD2} is the differential channel-to-channel skew of any event on the same device. This specification applies to devices having multiple receivers within the integrated circuit.

Note 9: t_{SKD3} , part to part skew, is the differential channel-to-channel skew of any event between devices. This specification applies to devices at the same V_{CC} and within 5°C of each other within the operating temperature range.

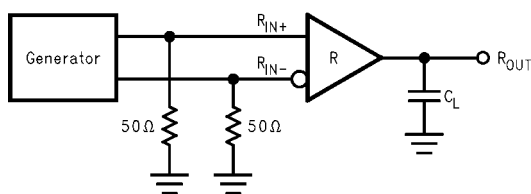
Note 10: t_{SKD4} , part to part skew, is the differential channel-to-channel skew of any event between devices. This specification applies to devices over the recommended operating temperature and voltage ranges, and across process distribution. t_{SKD4} is defined as $I_{Max} - I_{Min}$ differential propagation delay.

Note 11: V_{CC} is always higher than R_{IN+} and R_{IN-} voltage. R_{IN+} and R_{IN-} are allowed to have voltage range -0.05V to $+3.05\text{V}$. V_{ID} is not allowed to be greater than 100 mV when $V_{CM} = 0\text{V}$ or 3V .

Note 12: f_{MAX} generator input conditions: $t_r = t_f < 1 \text{ ns}$ (0% to 100%), 50% duty cycle, differential (1.05V to 1.35 peak to peak). Output criteria: 60%/40% duty cycle, V_{OL} (max 0.4V), V_{OH} (min 2.7V), load = 15 pF (stray plus probes).

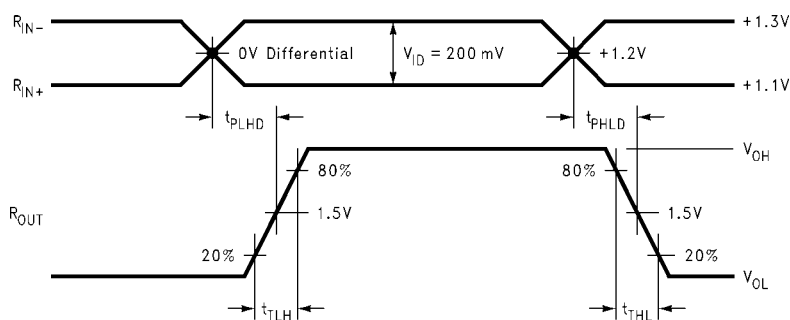
Note 13: For T_A between 85°C and 105°C the maximum switching speed is 200 Mbps for data or 100 MHz for clock signals.

Parameter Measurement Information



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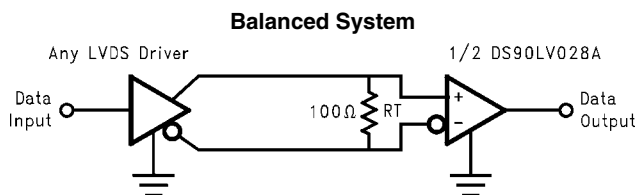
FIGURE 1. Receiver Propagation Delay and Transition Time Test Circuit



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FIGURE 2. Receiver Propagation Delay and Transition Time Waveforms

Typical Application



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FIGURE 3. Point-to-Point Application

Applications Information

General application guidelines and hints for LVDS drivers and receivers may be found in the following application notes: LVDS Owner's Manual (lit #550062-003), AN-808, AN-977, AN-971, AN-916, AN-805, AN-903.

LVDS drivers and receivers are intended to be primarily used in an uncomplicated point-to-point configuration as is shown in *Figure 3*. This configuration provides a clean signaling environment for the fast edge rates of the drivers. The receiver is connected to the driver through a balanced media which may be a standard twisted pair cable, a parallel pair cable, or simply PCB traces. Typically the characteristic impedance of the media is in the range of 100Ω. A termination resistor of 100Ω should be selected to match the media, and is located as close to the receiver input pins as possible. The termination resistor converts the driver output (current mode) into a voltage that is detected by the receiver. Other configurations are possible such as a multi-receiver configuration, but the effects of a mid-stream connector(s), cable stub(s), and other impedance discontinuities as well as ground shifting, noise margin limits, and total termination loading must be taken into account.

The DS90LV028AQ differential line receiver is capable of detecting signals as low as 100 mV, over a ±1V common-mode range centered around +1.2V. This is related to the driver offset voltage which is typically +1.2V. The driven signal is centered around this voltage and may shift ±1V around this center point. The ±1V shifting may be the result of a ground potential difference between the driver's ground reference and the receiver's ground reference, the common-mode effects of coupled noise, or a combination of the two. The AC parameters of both receiver input pins are optimized for a recommended operating input voltage range of 0V to +2.4V (measured from each pin to ground). The device will operate for receiver input voltages up to V_{CC} , but exceeding V_{CC} will turn on the ESD protection circuitry which will clamp the bus voltages.

POWER DECOUPLING RECOMMENDATIONS

Bypass capacitors must be used on power pins. Use high frequency ceramic (surface mount is recommended) 0.1μF and 0.01μF capacitors in parallel at the power supply pin with the smallest valued capacitor closest to the device supply pin. Additional scattered capacitors over the printed circuit board will improve decoupling. Multiple vias should be used to connect the decoupling capacitors to the power planes. A 10μF (35V) or greater solid tantalum capacitor should be connected at the power entry point on the printed circuit board between the supply and ground.

PC BOARD CONSIDERATIONS

Use at least 4 PCB board layers (top to bottom): LVDS signals, ground, power, TTL signals.

Isolate TTL signals from LVDS signals, otherwise the TTL signals may couple onto the LVDS lines. It is best to put TTL and LVDS signals on different layers which are isolated by a power/ground plane(s).

Keep drivers and receivers as close to the (LVDS port side) connectors as possible.

DIFFERENTIAL TRACES

Use controlled impedance traces which match the differential impedance of your transmission medium (ie. cable) and termination resistor. Run the differential pair trace lines as close together as possible as soon as they leave the IC (stubs should be < 10mm long). This will help eliminate reflections

and ensure noise is coupled as common-mode. In fact, we have seen that differential signals which are 1mm apart radiate far less noise than traces 3mm apart since magnetic field cancellation is much better with the closer traces. In addition, noise induced on the differential lines is much more likely to appear as common-mode which is rejected by the receiver.

Match electrical lengths between traces to reduce skew. Skew between the signals of a pair means a phase difference between signals which destroys the magnetic field cancellation benefits of differential signals and EMI will result! (Note that the velocity of propagation, $v = c/E$, where c (the speed of light) = 0.2997mm/ps or 0.0118 in/ps). Do not rely solely on the autoroute function for differential traces. Carefully review dimensions to match differential impedance and provide isolation for the differential lines. Minimize the number of vias and other discontinuities on the line.

Avoid 90° turns (these cause impedance discontinuities). Use arcs or 45° bevels.

Within a pair of traces, the distance between the two traces should be minimized to maintain common-mode rejection of the receivers. On the printed circuit board, this distance should remain constant to avoid discontinuities in differential impedance. Minor violations at connection points are allowable.

TERMINATION

Use a termination resistor which best matches the differential impedance or your transmission line. The resistor should be between 90Ω and 130Ω. Remember that the current mode outputs need the termination resistor to generate the differential voltage. LVDS will not work correctly without resistor termination. Typically, connecting a single resistor across the pair at the receiver end will suffice.

Surface mount 1% - 2% resistors are the best. PCB stubs, component lead, and the distance from the termination to the receiver inputs should be minimized. The distance between the termination resistor and the receiver should be < 10mm (12mm MAX).

INPUT FAILSAFE BIASING

External pull up and pull down resistors may be used to provide enough of an offset to enable an input failsafe under open-circuit conditions. This configuration ties the positive LVDS input pin to VDD thru a pull up resistor and the negative LVDS input pin is tied to GND by a pull down resistor. The pull up and pull down resistors should be in the 5kΩ to 15kΩ range to minimize loading and waveform distortion to the driver. The common-mode bias point ideally should be set to approximately 1.2V (less than 1.75V) to be compatible with the internal circuitry. Please refer to application note AN-1194, "Failsafe Biasing of LVDS Interfaces" for more information.

PROBING LVDS TRANSMISSION LINES

Always use high impedance (> 100kΩ), low capacitance (< 2 pF) scope probes with a wide bandwidth (1 GHz) scope. Improper probing will give deceiving results.

CABLES AND CONNECTORS, GENERAL COMMENTS

When choosing cable and connectors for LVDS it is important to remember:

Use controlled impedance media. The cables and connectors you use should have a matched differential impedance of about 100Ω. They should not introduce major impedance discontinuities.

Balanced cables (e.g. twisted pair) are usually better than unbalanced cables (ribbon cable, simple coax) for noise re-

duction and signal quality. Balanced cables tend to generate less EMI due to field canceling effects and also tend to pick up electromagnetic radiation a common-mode (not differential mode) noise which is rejected by the receiver.

For cable distances $< 0.5M$, most cables can be made to work effectively. For distances $0.5M \leq d \leq 10M$, CAT 3 (category 3) twisted pair cable works well, is readily available and relatively inexpensive.

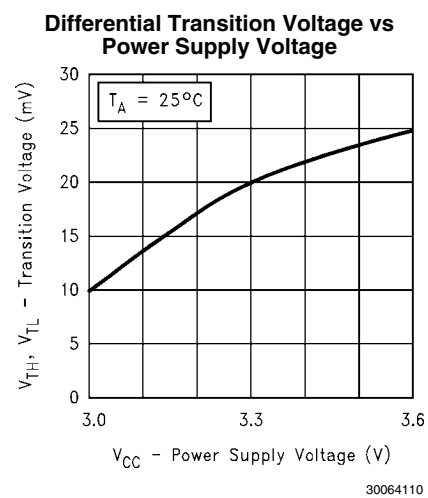
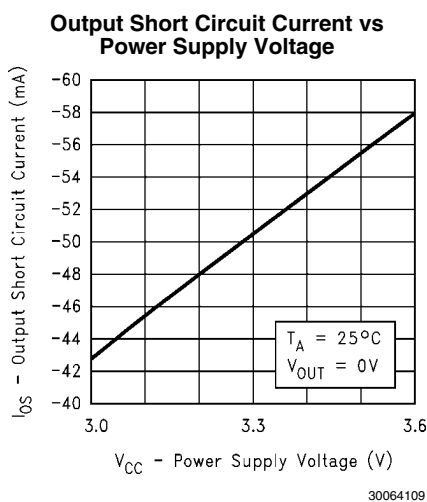
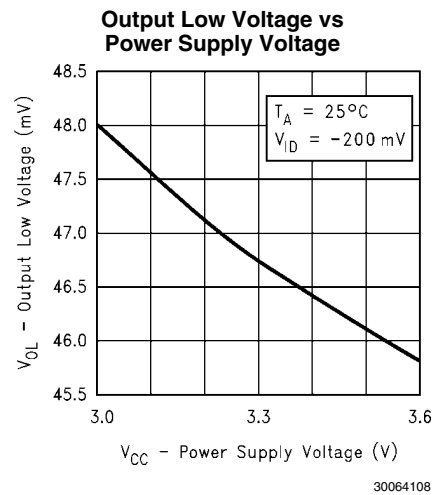
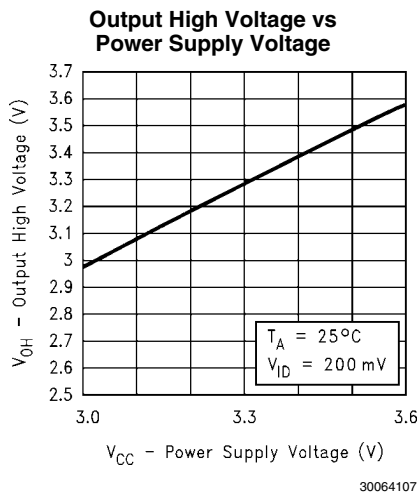
Pin Descriptions

Pin No.	Name	Description
1, 4	R _{IN-}	Inverting receiver input pin
2, 3	R _{IN+}	Non-inverting receiver input pin
6, 7	R _{OUT}	Receiver output pin
8	V _{CC}	Power supply pin, $+3.3V \pm 0.3V$
5	GND	Ground pin

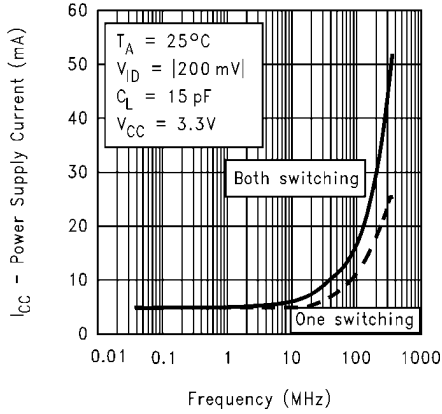
Ordering Information

Operating Temperature	Package Type/Number	Order Number
-40°C to +85°C	SOP/M08A	DS90LV028AQMA

Typical Performance Curves

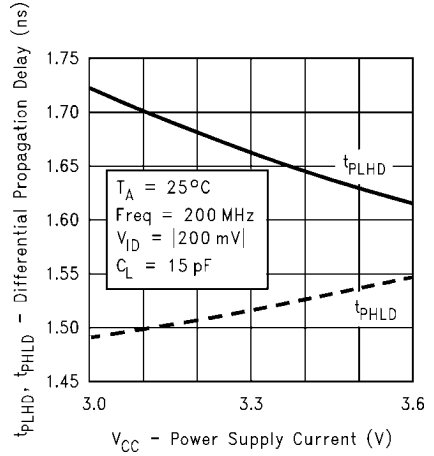


Power Supply Current vs Frequency



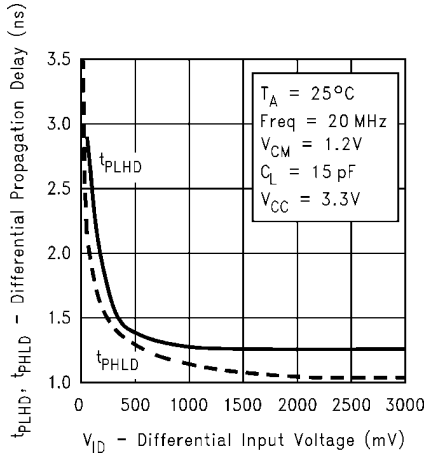
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Differential Propagation Delay vs Power Supply Voltage



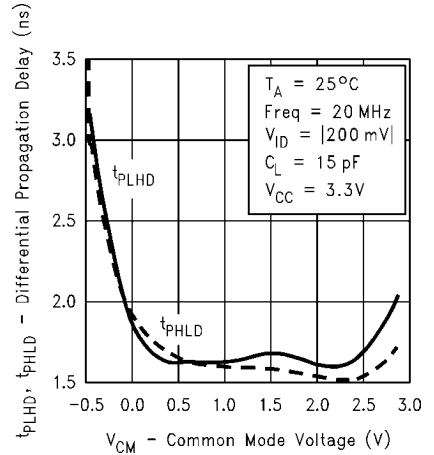
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Differential Propagation Delay vs Differential Input Voltage



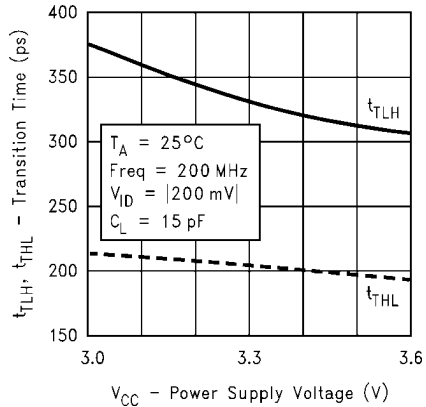
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Differential Propagation Delay vs Common-Mode Voltage



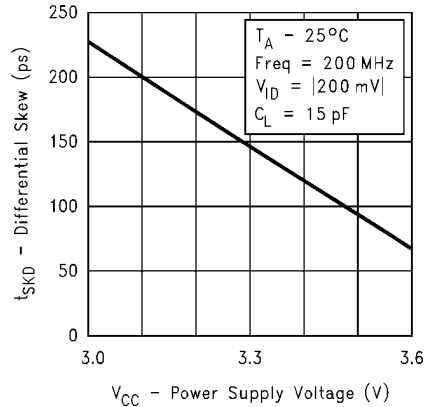
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Transition Time vs Power Supply Voltage



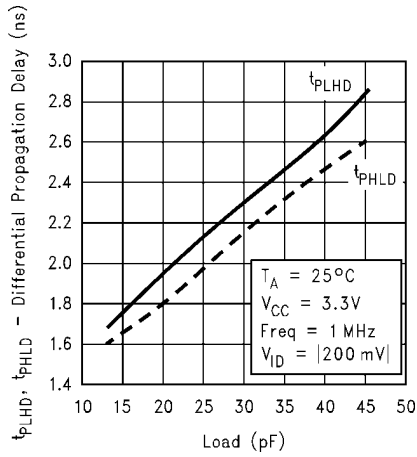
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Differential Skew vs Power Supply Voltage



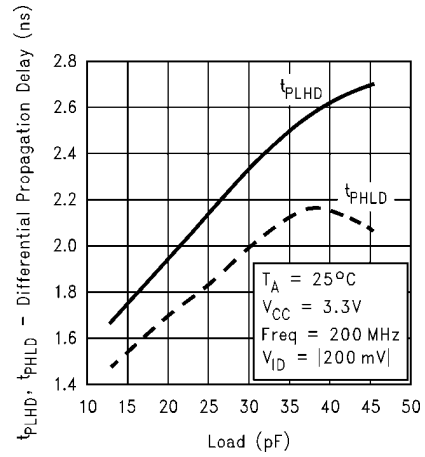
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Differential Propagation Delay vs Load



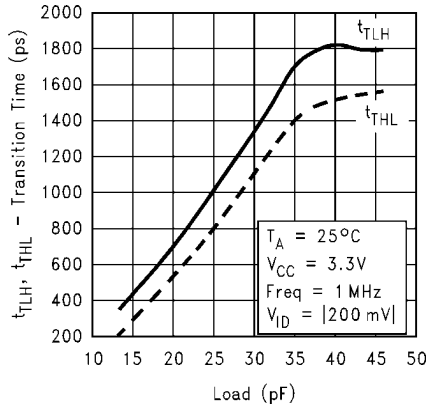
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Differential Propagation Delay vs Load



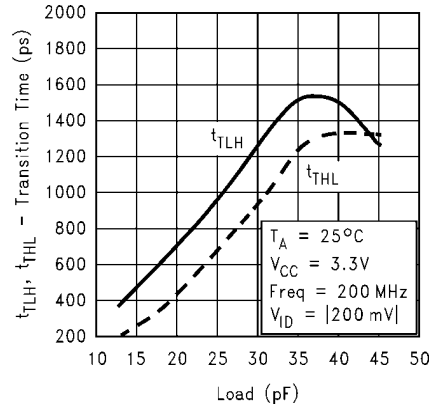
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Transition Time vs Load



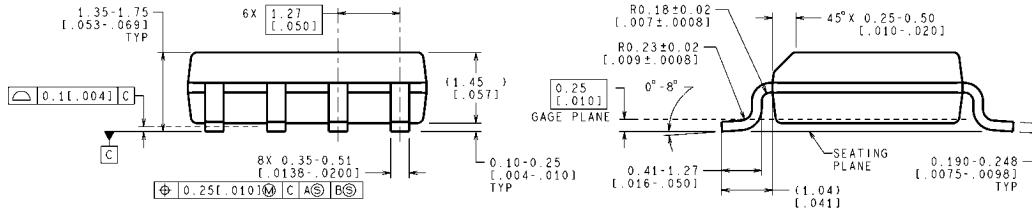
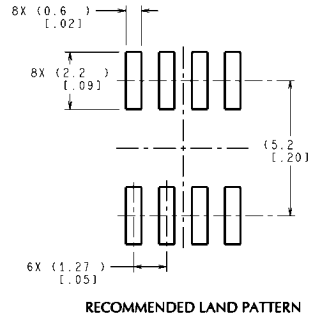
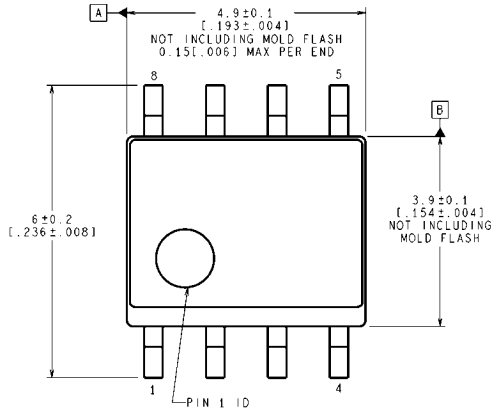
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Transition Time vs Load



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Physical Dimensions inches (millimeters) unless otherwise noted



CONTROLLING DIMENSION IS MILLIMETER
VALUES IN [] ARE INCHES
DIMENSIONS IN () FOR REFERENCE ONLY

8-Lead (0.150 Wide) Molded Small Outline Package, JEDEC
Order Number DS90LV028AQMA
NS Package Number M08A

M08A (Rev L)

Notes

Notes

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