



Configuration Devices for ACEX, APEX, FLEX & Mercury Devices

March 2001, ver. 11

Data Sheet

Features

- Serial device family for configuring ACEX™, APEX™ (including APEX 20K, APEX 20KC, and APEX 20KE), FLEX® (FLEX 10KE and FLEX 10KA), and Mercury™ devices
- Easy-to-use 4-pin interface to ACEX, APEX, FLEX, and Mercury devices
- Low current during configuration and near-zero standby current
- 5.0-V and 3.3-V operation
- Software design support with the Altera® Quartus™ and MAX+PLUS® II development systems for Windows-based PCs as well as Sun SPARCstation, and HP 9000 Series 700/800
- Programming support with Altera's Master Programming Unit (MPU) and programming hardware from Data I/O, BP Microsystems, and other manufacturers
- Available in compact plastic packages (see [Figures 1 and 2](#))
 - 8-pin plastic dual in-line package (PDIP)
 - 20-pin plastic J-lead chip carrier (PLCC) package
 - 32-pin plastic thin quad flat pack (TQFP) package
- EPC2 device has reprogrammable Flash configuration memory
 - 5.0-V and 3.3-V in-system programmability (ISP) through the built-in IEEE Std. 1149.1 Joint Test Action Group (JTAG) interface
 - Built-in JTAG boundary-scan test (BST) circuitry compliant with IEEE Std. 1149.1
 - ISP circuitry is compatible with IEEE Std. 1532 for EPC2 configuration device
 - Supports programming through Serial Vector Format Files (.svf), Jam™ Standard Test and Programming Language (STAPL) Files (.jam), Jam STAPL Byte-Code Files (.jbc), and the MAX+PLUS II software via the MasterBlaster™, ByteBlasterMV™, or BitBlaster™ download cable
 - nINIT_CONF pin allows a JTAG instruction to initiate APEX, FLEX, or Mercury device configuration
 - Can be programmed with Programmer Object Files (.pof) for EPC1 and EPC1441 devices
 - Available in 20-pin PLCC and 32-pin TQFP packages

Functional Description

With SRAM-based devices, configuration data must be reloaded each time the system initializes, or when new configuration data is needed. Altera configuration devices store configuration data for SRAM-based ACEX, APEX, FLEX, and Mercury devices. [Table 1](#) lists Altera configuration devices.

Device	Description
EPC2	1,695,680 × 1-bit device with 5.0-V or 3.3-V operation
EPC1	1,046,496 × 1-bit device with 5.0-V or 3.3-V operation
EPC1441	440,800 × 1-bit device with 5.0-V or 3.3-V operation
EPC1213	212,942 × 1-bit device with 5.0-V operation
EPC1064	65,536 × 1-bit device with 5.0-V operation
EPC1064V	65,536 × 1-bit device with 3.3-V operation

[Table 2](#) lists the configuration device used with each ACEX, APEX, FLEX and Mercury device.

ACEX, APEX, FLEX & Mercury Device	Configuration Device
EP20K30E	EPC2, EPC1, or EPC1441
EP20K60E	EPC2 or EPC1
EP20K100, EP20K100E	EPC2 or EPC1
EP20K160E	EPC2
EP20K200, EP20K200E	Two EPC2 devices (1)
EP20K300E	Two EPC2 devices (1)
EP20K400, EP20K400E	Three EPC2 devices (1)
EP20K600E	Four EPC2 devices (1)
EP20K1000E	Six EPC2 devices (1)
EP20K1500E	Eight EPC2 devices (1)
EP1K10	EPC2, EPC1, or EPC1441
EP1K30	EPC2, EPC1, or EPC1441
EP1K50	EPC2 or EPC1
EP1K100	EPC2 or two EPC1 devices
EPF10K10, EPF10K10A	EPC2, EPC1, or EPC1441
EPF10K20	EPC2, EPC1, or EPC1441
EPF10K30E	EPC2 or EPC1
EPF10K30, EPF10K30A	EPC2, EPC1, or EPC1441
EPF10K40	EPC2 or EPC1

Table 2. Appropriate Configuration Device for Each ACEX, APEX, FLEX & Mercury Device (Part 2 of 2)

ACEX, APEX, FLEX & Mercury Device	Configuration Device
EPF10K50, EPF10K50V, EPF10K50E	EPC2 or EPC1
EPF10K70	EPC2 or EPC1
EPF10K100, EPF10K100A, EPF10K100B, EPF10K100E	EPC2 or two EPC1 devices
EPF10K130V	EPC2 or two EPC1 devices
EPF10K130E	Two EPC2 or two EPC1 devices
EPF10K200E	Two EPC2 or three EPC1 devices
EPF10K250A	Two EPC2 or four EPC1 devices
EPF8282A	EPC1, EPC1441, or EPC1064
EPF8282AV	EPC1, EPC1441, or EPC1064V
EPF8452A	EPC1, EPC1441, EPC1064, or EPC1213
EPF8636A	EPC1, EPC1441, or EPC1213
EPF8820A	EPC1, EPC1441, or EPC1213
EPF81188A	EPC1, EPC1441, or EPC1213
EPF81500A	EPC1 or EPC1441
EPF6010A	EPC1 or EPC1441
EPF6016, EPF6016A	EPC1 or EPC1441
EPF6024A	EPC1 or EPC1441
EP1M120	EPC2 or EPC16
EP1M350	EPC16 or three EPC2 devices

Note:

- (1) This device can be configured by a smaller number of EPC16 configuration devices. For more information, see the [EPC16 Configuration Device Data Sheet](#).

Table 3 shows which configuration devices can be used with each device family.

Table 3. Configuration Device & PLD Compatibility

PLD	Configuration Device			
	EPC2	EPC1	EPC1441	EPC1213 EPC1064 EPC1064V
ACEX 1K (1)	✓	✓	✓	
APEX 20K (1)	✓	✓	✓	
FLEX 10K (1)	✓	✓	✓	
FLEX 10KE (1)	✓	✓		

<i>Table 3. Configuration Device & PLD Compatibility</i>				
PLD	Configuration Device			
	EPC2	EPC1	EPC1441	EPC1213 EPC1064 EPC1064V
FLEX 8000		✓	✓	✓
FLEX 6000		✓	✓	
Mercury (1)	✓	✓	✓	

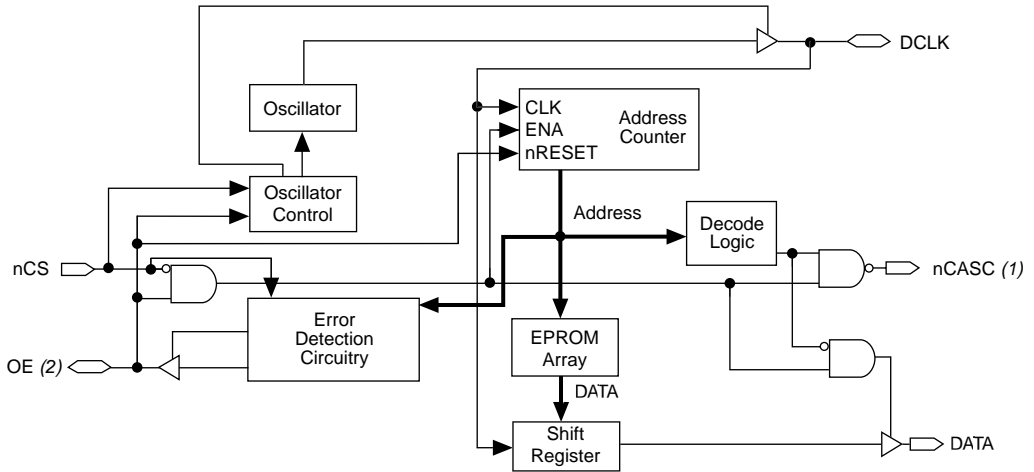
Note to Table:

- (1) EPC16 configuration devices support this device. For more information, see the [EPC16 Configuration Device Data Sheet](#).

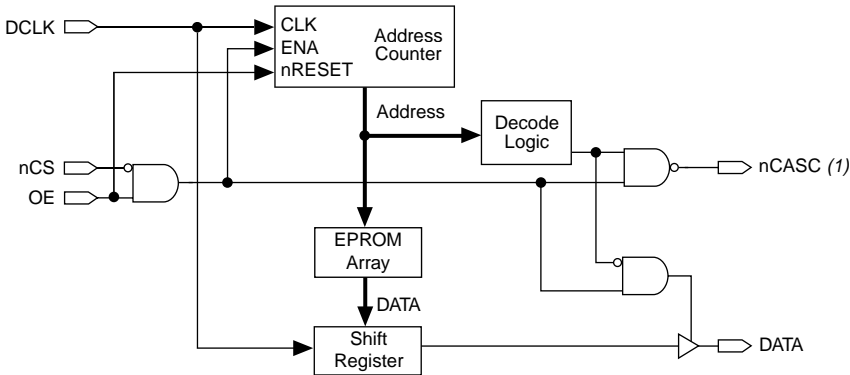
Figure 3 shows the configuration device block diagram.

Figure 3. Configuration Device Block Diagram

ACEX 1K, APEX 20K, FLEX 10K, & FLEX 6000 Device Configuration Using an EPC2, EPC1, or EPC1441 Device



FLEX 8000 Device Configuration Using an EPC1, EPC1441, EPC1213, EPC1064, or EPC1064V Device



Notes:

- (1) The EPC1441, EPC1064, and EPC1064V devices do not support data cascading. The EPC2, EPC1, and EPC1213 devices support data cascading.
- (2) The OE pin is a bidirectional open-drain pin.

Device Configuration

The control signals for configuration devices— \overline{nCS} , OE , and $DCLK$ —interface directly with ACEX, APEX, FLEX, and Mercury device control signals. All ACEX, APEX, FLEX, and Mercury devices can be configured by a configuration device without requiring an external intelligent controller.

The configuration device's OE and \overline{nCS} pins control the tri-state buffer on the $DATA$ output pin, and enable the address counter (and the oscillator in EPC2, EPC1, and EPC1441 devices). When OE is driven low, the configuration device resets the address counter and tri-states its $DATA$ pin. The \overline{nCS} pin controls the output of the configuration device. If \overline{nCS} is held high after the OE reset pulse, the counter is disabled and the $DATA$ output pin is tri-stated. When \overline{nCS} is driven low, the counter and $DATA$ output pin are enabled. When OE is driven low again, the address counter is reset and the $DATA$ output pin is tri-stated, regardless of the state of \overline{nCS} .



The EPC2, EPC1, and EPC1441 devices determine the operation mode and whether the ACEX 1K, APEX 20K, FLEX 10K, FLEX 8000, FLEX 6000, or Mercury protocols should be used when OE is driven high.

When the configuration device has driven out all of its data and has driven \overline{nCASC} low, the device tri-states the $DATA$ pin to avoid contention with other configuration devices.

The EPC2 device allows the user to initiate configuration of the ACEX, APEX, FLEX, or Mercury device via an additional pin, $\overline{nINIT_CONF}$, that can be tied to the $\overline{nCONFIG}$ pin of the ACEX, APEX, FLEX, or Mercury device(s) to be configured. A JTAG instruction causes the EPC2 device to drive $\overline{nINIT_CONF}$ low, which in turn pulls $\overline{nCONFIG}$ low. The EPC2 device then drives $\overline{nINIT_CONF}$ high to start configuration. When the JTAG state machine exits this state, $\overline{nINIT_CONF}$ releases $\overline{nCONFIG}$ and configuration is initiated.

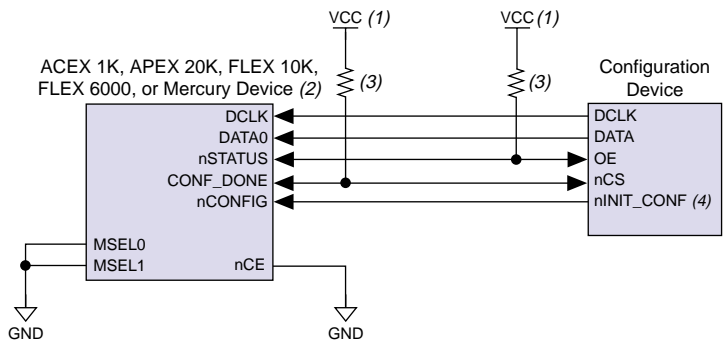


An EPC2 device can be programmed with a POF generated for an EPC1 or EPC1441 device, however, an EPC2 device cannot configure FLEX 6000 or FLEX 8000 devices. An EPC1 device can be programmed using a POF generated for an EPC1441 device.

ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000 & Mercury Device Configuration

ACEX 1K, APEX 20K, FLEX 10K, and Mercury devices can be configured with EPC2, EPC1, or EPC1441 devices. FLEX 6000 devices can be configured with EPC1 or EPC1441 devices. The EPC2, EPC1, or EPC1441 device stores configuration data in its EPROM array and serially clocks data out with an internal oscillator. The OE, nCS, and DCLK pins supply the control signals for the address counter and the output tri-state buffer. The configuration device sends a serial bitstream of configuration data to its DATA pin, which is routed to the DATA0 or DATA input pin on the ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury device. [Figure 4](#) shows an ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury device configured with a single EPC2, EPC1, or EPC1441 device.

Figure 4. ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury Device Configured with an EPC2, EPC1, or EPC1441 Configuration Device



Notes:

- (1) The pull-up resistor should be connected to the same supply voltage as the configuration device.
- (2) The diagram shows an ACEX 1K, APEX 20K, FLEX 10K or Mercury device, which has MSEL0 and MSEL1 tied to ground. For FLEX 6000 devices, MSEL is tied to ground, and the DATA0 pin is named DATA. EPC2 cannot be used with FLEX 6000 devices. All other connections are the same for ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000 and Mercury devices.
- (3) All pull-up resistors are 1 k Ω . APEX 20KE pull up resistors are 10 k Ω . The OE, nCS, and nINIT_CONF pins on EPC2 devices have internal, user-configurable 1-k Ω pull-up resistors. If internal pull-up resistors are used, external pull-up resistors should not be used on these pins.
- (4) The nINIT_CONF pin is only available on EPC2 devices and has an internal pull up of 1 k Ω that is always active. If nINIT_CONF is not available or not used, nCONFIG must be pulled to V_{CC} either directly or through a 1-k Ω resistor.

[Table 4](#) describes EPC2, EPC1, and EPC1441 pin functions during ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, and Mercury device configuration.

Table 4. EPC2, EPC1, & EPC1441 Pin Functions During ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000 & Mercury Configuration (Part 1 of 2)

Pin Name	Pin Number			Pin Type	Description
	8-Pin PDIP (1)	20-Pin PLCC	32-Pin TQFP (2)		
DATA	1	2	31	Output	Serial data output. The DATA pin is tri-stated before configuration when the nCS pin is high, and after the configuration device finishes sending its configuration data. This operation is independent of the device's position in the cascade chain.
DCLK	2	4	2	I/O	DCLK is a clock output when configuring with a single configuration device or when the configuration device is the first device in a configuration device chain. DCLK is a clock input for subsequent configuration devices in a configuration device chain. Rising edges on DCLK increment the internal address counter and present the next bit of data to the DATA pin. The counter is incremented only if the OE input is held high, the nCS input is held low, and all configuration data has not been transferred to the target device. When configuring with the first EPC2 or EPC1 device in a configuration device chain or with a single EPC1441 device, the DCLK pin drives low after configuration is complete or when OE is low.
OE (3)	3	8	7	Open-Drain I/O	Output enable (active high) and reset (active low). A low logic level resets the address counter. A high logic level enables DATA and permits the address counter to count. If this pin is low (reset) during configuration, the internal oscillator becomes inactive and DCLK drives low. See "Error Detection Circuitry" on page 17.
nCS (3)	4	9	10	Input	Chip select input (active low). A low input allows DCLK to increment the address counter and enables DATA to drive out. If the EPC1 or EPC2 is reset with nCS low, the device initializes as the first device in a configuration chain. If the EPC1 or EPC2 device is reset with nCS high, the device initializes as the subsequent device in the chain.
nCASC (4)	6	12	15	Output	Cascade select output (active low). This output goes low when the address counter has reached its maximum value. In a chain of EPC1 or EPC2 devices, the nCASC pin of one device is connected to the nCS pin of the next device, which permits DCLK to clock data from the next EPC1 or EPC2 device in the chain.

Table 4. EPC2, EPC1, & EPC1441 Pin Functions During ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000 & Mercury Configuration (Part 2 of 2)

Pin Name	Pin Number			Pin Type	Description
	8-Pin PDIP (1)	20-Pin PLCC	32-Pin TQFP (2)		
nINIT_CONF (3), (5)	–	13	16	Open-Drain Output	Allows the INIT_CONF JTAG instruction to initiate configuration. This pin is connected to the nCONFIG pin of the ACEX, APEX, FLEX or Mercury device to initiate configuration from the EPC2 via a JTAG instruction. If multiple EPC2 devices are used to configure an ACEX, APEX, FLEX or Mercury device, only the first EPC2 has its nINIT_CONF pin tied to the device's nCONFIG pin.
TDI (5)	–	11	13	Input	JTAG data input pin. Connect this pin to V _{CC} if the JTAG circuitry is not used.
TDO (5)	–	1	28	Output	JTAG data output pin. Do not connect this pin if the JTAG circuitry is not used.
TMS (5)	–	19	25	Input	JTAG mode select pin. Connect this pin to V _{CC} if the JTAG circuitry is not used.
TCK (5)	–	3	32	Input	JTAG clock pin. Connect this pin to ground if the JTAG circuitry is not used.
VCCSEL (5)	–	5	3	Input	Mode select for V _{CC} supply. VCCSEL must be connected to ground if the device uses a 5.0-V power supply (i.e., V _{CC} = 5.0 V). VCCSEL must be connected to V _{CC} if the device uses a 3.3-V power supply (i.e., V _{CC} = 3.3 V).
VPPSEL (5)	–	14	17	Input	Mode select for V _{PP} . VPPSEL must be connected to ground if V _{PP} uses a 5.0-V power supply (i.e., V _{PP} = 5.0 V). VPPSEL must be connected to V _{CC} if V _{PP} uses a 3.3-V power supply (i.e., V _{PP} = 3.3 V).
VPP (5)	–	18	23	Power	Programming power pin. For the EPC2 device, this pin is normally tied to V _{CC} . If the EPC2 V _{CC} is 3.3 V, V _{PP} can be tied to 5.0 V to improve in-system programming times. For EPC1 and EPC1441 devices, V _{PP} must be tied to V _{CC} .
VCC	7, 8	20	27	Power	Power pin.
GND	5	10	12	Ground	Ground pin. A 0.2-μF decoupling capacitor must be placed between the VCC and GND pins.

Notes:

- (1) This package is available for EPC1 and EPC1441 devices only.
- (2) This package is available for EPC2 and EPC1441 devices only.
- (3) The OE, nCS, and nINIT_CONF pins on EPC2 devices have internal, user-configurable 1-k Ω pull-up resistors. If internal pull-up resistors are used, external pull-up resistors should not be used on these pins.
- (4) The EPC1441 device does not support data cascading. EPC2 and EPC1 devices support data cascading.
- (5) This pin applies to the EPC2 device only.

ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000 & Mercury Device Configuration with Multiple EPC2 or EPC1 Configuration Devices

When configuration data for ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury devices exceeds the capacity of a single EPC2 or EPC1 device, multiple EPC2 or EPC1 devices can be cascaded together. (The EPC1441 device does not support data cascading.) If multiple EPC2 or EPC1 devices are required, the `nCASC` and `nCS` pins provide handshaking between the devices.

When configuring ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury devices with cascaded EPC2 or EPC1 devices, the position of the EPC2 or EPC1 device in the chain determines its operation. When the first or master device in a configuration device chain is powered-up or reset and the `nCS` pin is driven low, the master device controls configuration. The master device supplies all clock pulses to one or more ACEX, APEX, FLEX, or Mercury devices and to any subsequent slave devices during configuration. The master EPC2 or EPC1 device also provides the first stream of data to the ACEX, APEX, FLEX, or Mercury devices during multi-device configuration. After the master EPC2 or EPC1 device finishes sending configuration data, the master EPC2 or EPC1 device drives its `nCASC` pin low, which drives the `nCS` pin of the first slave EPC2 or EPC1 device low. This action causes the slave EPC2 or EPC1 device to send configuration data to the ACEX, APEX, FLEX, or Mercury devices.

The master EPC2 or EPC1 device clocks all subsequent slave devices until configuration is complete. Once all configuration data is transferred and the `nCS` pin on the master EPC2 or EPC1 device is driven high by the ACEX, APEX, FLEX, or Mercury device's `CONF_DONE` pin, the master EPC2 or EPC1 device clocks 16 additional cycles to initialize the ACEX, APEX, FLEX, or Mercury device(s). The master EPC2 or EPC1 device then goes into zero-power (idle) state. If `nCS` on the master EPC2 or EPC1 device is driven high before all configuration data is transferred, or if `nCS` is not driven high after all configuration data is transferred, the master EPC2 or EPC1 device drives the ACEX, APEX, FLEX, or Mercury device's `nSTATUS` pin low, indicating a configuration error.

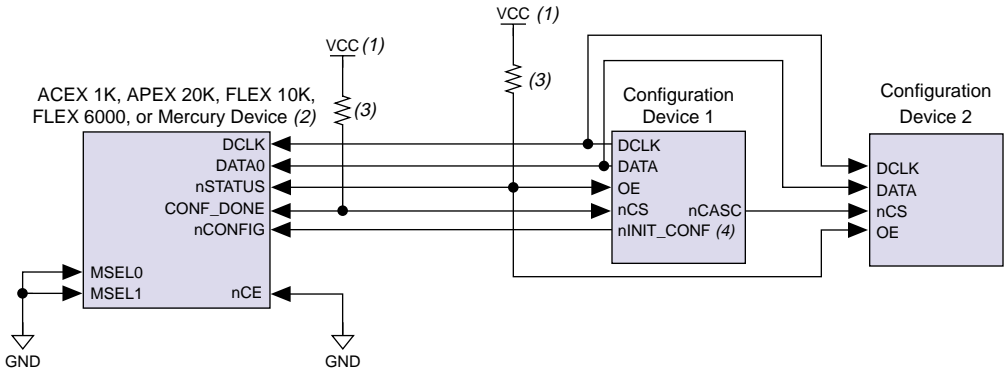
Configuration automatically restarts if the project is compiled with the *Auto-Restart Configuration on Frame Error* option turned on in the MAX+PLUS II software's **Global Project Device Options** dialog box (Assign menu).

Figure 5 shows an ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury device configured with two EPC2 or EPC1 devices. Additional EPC2 or EPC1 devices can be added by connecting `nCASC` to `nCS` of the subsequent slave EPC2 or EPC1 device in the chain and connecting `DCLK`, `DATA`, and `OE` in parallel.



A mixture of ACEX 1K, APEX 20K, APEX 20KE, and Mercury devices can be configured in the same chain. A mixture of FLEX 10K, FLEX 10KA, FLEX 10KE, and 5.0-V and 3.3-V FLEX 6000 devices can be configured in the same chain. See “Configuration Chain with Multiple Voltage Levels” on page 19.

Figure 5. ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury Device Configured with Two EPC2 or EPC1 Configuration Devices

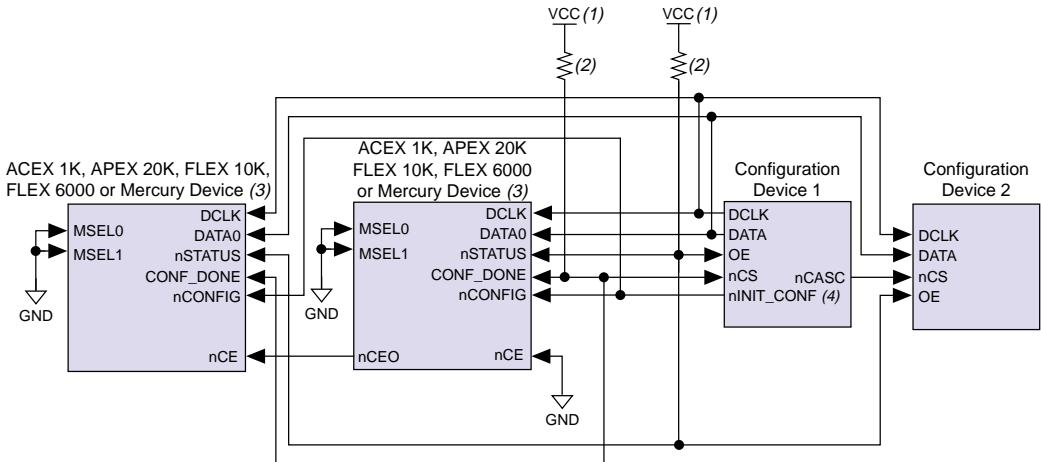


Notes:

- (1) The pull-up resistor should be connected to the same supply voltage as the configuration device.
- (2) The diagram shows an ACEX 1K, APEX 20K, FLEX 10K, or Mercury device, which has MSEL0 and MSEL1 tied to ground. For FLEX 6000 devices, MSEL is tied to ground, and the DATA0 pin is named DATA. EPC2 cannot be used with FLEX 6000 devices. All other connections are the same for ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, and Mercury devices.
- (3) All pull-up resistors are 1 k Ω (APEX 20KE pull-resistors are 10k Ω). The OE and nCS pins on EPC2 devices have internal, user-configurable 1-k Ω pull-up resistors. If internal pull-up resistors are used, external pull-up resistors should not be used on these pins.
- (4) The nINIT_CONF pin is only available on EPC2 devices and has an internal pull up of 1 k Ω that is always active. If nINIT_CONF is not available or not used, nCONFIG must be pulled to V_{CC} either directly or through a 1-k Ω resistor.

Figure 6 shows two ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury devices configured with two EPC2 or EPC1 devices.

Figure 6. Two ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury Devices Configured with Two EPC2 or EPC1 Configuration Devices



Notes:

- (1) The pull-up resistor should be connected to the same supply voltage as the configuration device.
- (2) The diagram shows an ACEX 1K, APEX 20K, FLEX 10K, or Mercury device, which has MSEL0 and MSEL1 tied to ground. For FLEX 6000 devices, MSEL is tied to ground, and the DATA0 pin is named DATA. EPC2 cannot be used with FLEX 6000 devices. All other connections are the same for ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, and Mercury devices.
- (3) All pull-up resistors are 1 k Ω (APEX 20KE pull-resistors are 10k Ω). The OE and nCS pins on EPC2 devices have internal, user-configurable 1-k Ω pull-up resistors. If internal pull-up resistors are used, external pull-up resistors should not be used on these pins.
- (4) The nINIT_CONF pin is only available on EPC2 devices and has an internal pull up of 1 k Ω that is always active. If nINIT_CONF is not available or not used, nCONFIG must be pulled to VCC either directly or through a 1-k Ω resistor.



For more information on ACEX 1K, APEX 20K, FLEX 10K, or FLEX 6000 device configuration, see [Application Note 116 \(Configuring ACEX 1K, APEX 20K, FLEX 10K & FLEX 6000 Devices\)](#).

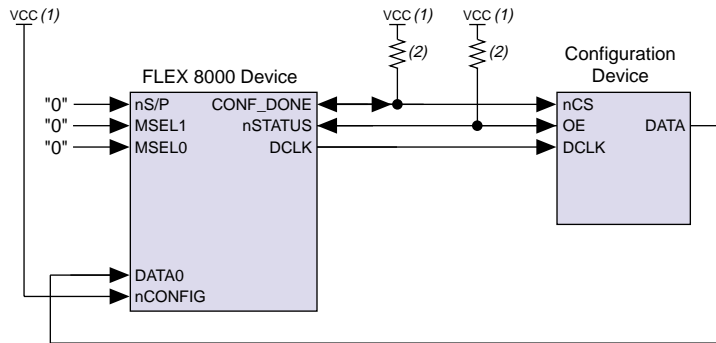
FLEX 8000 Device Configuration

FLEX 8000 devices differ from ACEX 1K, APEX 20K, FLEX 10K, and FLEX 6000 devices in that they have internal oscillators that can provide a DCLK signal to the configuration device. The configuration device sends configuration data out as a serial bitstream on the DATA output pin. This data is routed into the FLEX 8000 device via the DATA0 input pin. The EPC1, EPC1441, EPC1213, EPC1064, and EPC1064V configuration devices support this type of configuration.

EPC1 and EPC1441 devices can replace the EPC1213, EPC1064, and EPC1064V configuration devices. The EPC1 or EPC1441 device automatically emulates the EPC1213, EPC1064, or EPC1064V when it is programmed with the appropriate POF. When the EPC1 or EPC1441 device is programmed with an EPC1213, EPC1064, or EPC1064V POF, the FLEX 8000 device drives the EPC1 or EPC1441 device's \overline{OE} pin high and clocks the EPC1 or EPC1441 device. One EPC1 device can store more configuration data than the EPC1064, EPC1064V, EPC1213, or EPC1441 device. Therefore, designers can use one type of configuration device for all FLEX devices. In addition, a single EPC1 or EPC1441 device can configure any FLEX 8000 device.

For multi-device configuration of FLEX 8000 devices, the $nCASC$ and nCS pins provide handshaking between multiple configuration devices, allowing several cascaded EPC1 or EPC1213 devices to serially configure multiple FLEX 8000 devices. The EPC1441, EPC1064, and EPC1064V do not support data cascading. **Figure 7** shows a FLEX 8000 device configured with a single EPC1, EPC1441, EPC1213, EPC1064, or EPC1064V configuration device.

Figure 7. FLEX 8000 Device Configured with an EPC1, EPC1441, EPC1213, EPC1064, or EPC1064V Configuration Device

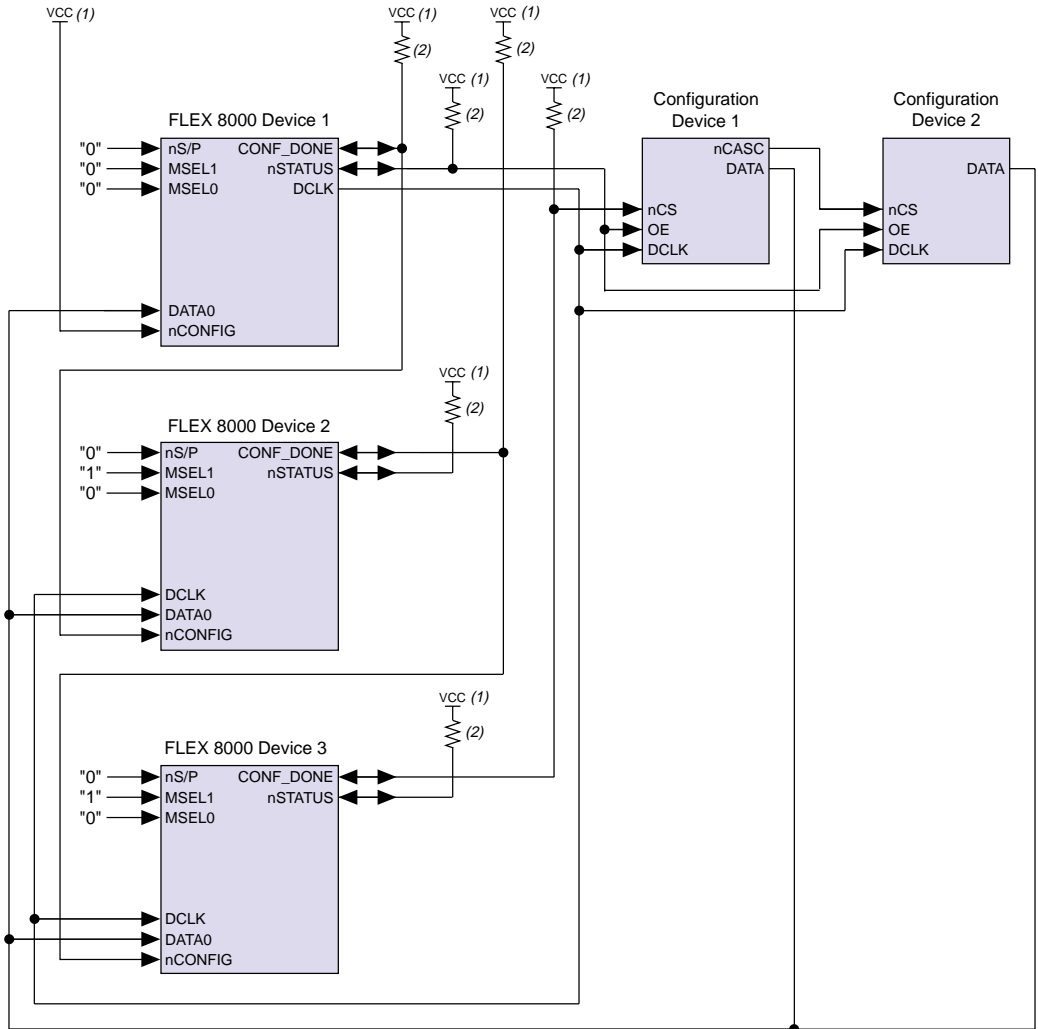


Notes:

- (1) The pull-up resistor should be connected to the same supply voltage as the configuration device.
- (2) All pull-up resistors are 1 k Ω .

Figure 8 shows three FLEX 8000 devices configured with two EPC1 or EPC1213 configuration devices.

Figure 8. FLEX 8000 Multi-Device Configuration with Two EPC1 or EPC1213 Configuration Devices



Notes:

- (1) The pull-resistor should be connected to the same supply voltage as the configuration device.
- (2) All pull-up resistors are 1 k Ω .

Table 5 describes the pin functions of all configuration devices during FLEX 8000 device configuration.

Pin Name	Pin Number			Pin Type	Description
	8-Pin PDIP (1)	20-Pin PLCC	32-Pin TQFP (2)		
DATA	1	2	31	Output	Serial data output. The DATA pin is tri-stated before configuration when the nCS pin is high and after the configuration device finishes sending its configuration data. This operation is independent of the device's position in the cascade chain.
DCLK	2	4	2	Input	DCLK is a clock input when using EPC1, EPC1213, EPC1064, and EPC1064V configuration devices. Rising edges on DCLK increment the internal address counter and present the next bit of data to the DATA pin. The counter is incremented only if the OE input is held high, the nCS input is held low, and all configuration data has not been transferred to the target device.
OE	3	8	7	Open-Drain I/O	Output enable (active high) and reset (active low). A low logic level resets the address counter. A high logic level enables DATA and permits the address counter to count.
nCS (3)	4	9	10	Input	Chip-select input (active low). A low input allows DCLK to increment the address counter and enables DATA.
nCASC	6	12	15	Output	Cascade-select output (active low). This output goes low when the address counter has reached its maximum value. The nCASC output is usually connected to the nCS input of the next device in a configuration chain, so the next DCLK clocks data out of the next device.
VCC	7, 8	20	27	Power	Power pin.
GND	5	10	12	Ground	Ground pin. A 0.2- μ F decoupling capacitor must be placed between the VCC and GND pins.

Notes:

- (1) This package is available for EPC1, EPC1441, EPC1213, EPC1064, and EPC1064V devices only.
- (2) This package is available for EPC1441, EPC1064, and EPC1064V devices only.
- (3) The EPC1441, EPC1064, and EPC1064V devices do not support data cascading. The EPC1 and EPC1213 devices support data cascading for FLEX 8000 devices.



For more information on FLEX 8000 device configuration, see the following documents:

- [Application Note 33 \(Configuring FLEX 8000 Devices\)](#)
- [Application Note 38 \(Configuring Multiple FLEX 8000 Devices\)](#)

Power & Operation

This section describes Power-On Reset (POR) delay, error detection, and 3.3-V and 5.0-V operation of Altera configuration devices.

Power-On Reset

During initial power-up, a POR delay occurs to permit voltage levels to stabilize. When configuring an ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury device with an EPC2, EPC1, or EPC1441 device, the POR delay occurs inside the configuration device, and the POR delay is a maximum of 100 ms. When configuring a FLEX 8000 device with an EPC1213, EPC1064, or EPC1064V device, the POR delay occurs inside the FLEX 8000 device, and the POR delay is typically 100 ms, with a maximum of 200 ms.

Error Detection Circuitry

The EPC2, EPC1, and EPC1441 configuration devices have built-in error detection circuitry for configuring ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, and Mercury devices only.

Built-in error-detection circuitry uses the `nCS` pin of the configuration device, which monitors the `CONF_DONE` pin on the ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury device. An error condition occurs if the `CONF_DONE` pin does not go high after all the configuration data has been sent, or if the `CONF_DONE` pin goes high before the configuration device has completed sending configuration data. When an error condition occurs, the configuration device drives its `OE` pin low, which drives the ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury device's `nSTATUS` pin low, indicating an error. After an error, configuration automatically restarts if the *Auto-Restart Configuration on Frame Error* option is turned on in the **Global Project Device Options** dialog box (Assign menu) in the MAX+PLUS II software. For APEX 20K and Mercury devices, the Quartus software provides a similar option.

In addition, if the ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury device detects a cyclic redundancy code (CRC) error in the received data, it may also flag the error by driving `nSTATUS` low. This low signal on `nSTATUS` resets the configuration device, allowing reconfiguration. CRC checking is performed when configuring all ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, and Mercury devices.

3.3-V or 5.0-V Operation

EPC2, EPC1, and EPC1441 devices can configure 5.0-V, 3.3-V, or 2.5-V devices. For each configuration device, an option must be set for 5.0-V or 3.3-V operation. For EPC1 and EPC1441 configuration devices, the *Use Low-Voltage Configuration EPROM* option in the **Global Project Device Options** dialog box (Assign menu) in the MAX+PLUS II software sets this parameter. (For APEX 20K and Mercury devices, the Quartus software provides a similar option.) For EPC2 devices, this option is set externally by the VCCSEL pin. In addition, the EPC2 device has an externally controlled option, set by the VPPSEL pin, to adjust the programming voltage to 5.0 V or 3.3 V.

The functions of the VCCSEL and VPPSEL pins are described below.

- **VCCSEL pin**—For EPC2 configuration devices, 5.0-V or 3.3-V operation is controlled by the VCCSEL option pin. The device functions in 5.0-V mode when VCCSEL is connected to GND; the device functions in 3.3-V mode when VCCSEL is connected to V_{CC}.
- **VPPSEL pin**—The EPC2 VPP programming power pin is normally tied to V_{CC}. For EPC2 devices operating with a 3.3-V supply, it is possible to improve EPC2 in-system programming times by providing VPP with a 5.0-V supply. For all other devices, VPP must be tied to V_{CC}. The EPC2 device's VPPSEL pin must be set in accordance with the EPC2 VPP pin. If the VPP pin is supplied by a 5.0-V supply, VPPSEL must be connected to GND; if the VPP pin is supplied by a 3.3-V power supply, VPPSEL must be connected to V_{CC}.

Table 6 describes the relationship between the V_{CC} and V_{PP} voltage levels and the required logic level for VCCSEL and VPPSEL (i.e., high or low logic level).

V _{CC} Voltage Level (V)	V _{PP} Voltage Level (V)	VCCSEL Pin Logic Level	VPPSEL Pin Logic Level
3.3	3.3	High	High
3.3	5.0	High	Low
5.0	5.0	Low	Low

For EPC1 and EPC1441 configuration devices, 3.3-V or 5.0-V operation is controlled by a programming bit in the POF. The programming bit value is determined by the core supply voltage of the targeted device during design compilation with the MAX+PLUS II software. For example, EPC1 devices are programmed automatically to operate in 3.3-V mode when configuring FLEX 10KA devices, which have a V_{CC} voltage of 3.3 V. In this example, the EPC1 device's VCC pin is connected to a 3.3-V power supply.

Designers may choose to set the configuration device for low voltage when using the MultiVolt™ feature, which allows an ACEX, APEX, FLEX, or Mercury device to bridge between systems operating with different voltages. When compiling for 3.3-V FLEX 6000 devices, set the configuration device for low-voltage operation. To set the EPC1 and EPC1441 configuration devices for low-voltage operation, turn on the *Low-Voltage I/O* option in the **Global Project Device Options** dialog box (Assign menu) in the MAX+PLUS II software.

Configuration Chain with Multiple Voltage Levels

An EPC2 or EPC1 device can configure a device chain with multiple voltage levels. All 3.3-V and 2.5-V ACEX, APEX, FLEX, and Mercury devices can be driven by higher-voltage signals.

When configuring a mixed-voltage device chain, the ACEX, APEX, FLEX and Mercury devices' V_{CCINT} and V_{CCIO} pins may be connected to 2.5 V, 3.3 V, or 5.0 V, depending upon the device. The configuration device may be powered at 3.3 V or 5.0 V. If an EPC1, EPC1441, EPC1213, EPC1064, or EPC1064V configuration device is powered at 3.3 V, the nSTATUS and CONF_DONE pull-up resistors must be connected to 3.3 V. If these configuration devices are powered at 5.0 V, the nSTATUS and CONF_DONE pull-up resistors must be connected to 3.3 V or 5.0 V.

At 3.3-V operation, all EPC2 inputs are 5.0-V tolerant, except DATA, DCLK, and nCASC. The DATA, DCLK, and nCEO pins are used only to interface between the EPC2 and the ACEX 1K, APEX 20K, FLEX 10K, FLEX 6000, or Mercury device it is configuring. The voltage tolerances of all EPC2 pins at 5.0 V and 3.3 V are listed in [Table 7](#).

Pin	5.0-V Operation		3.3-V Operation	
	5.0-V Tolerant	3.3-V Tolerant	5.0-V Tolerant	3.3-V Tolerant
DATA	✓	✓		✓
DCLK	✓	✓		✓

Table 7. EPC2 Input & Bidirectional Pin Voltage Tolerance

Pin	5.0-V Operation		3.3-V Operation	
	5.0-V Tolerant	3.3-V Tolerant	5.0-V Tolerant	3.3-V Tolerant
nCASC	✓	✓		✓
OE	✓	✓	✓	✓
nCS	✓	✓	✓	✓
VCCSEL	✓	✓	✓	✓
VPPSEL	✓	✓	✓	✓
nINIT_CONF	✓	✓	✓	✓
TDI	✓	✓	✓	✓
TMS	✓	✓	✓	✓
TCK	✓	✓	✓	✓



For more information on ACEX 1K, APEX 20K, FLEX 10K, FLEX 8000, FLEX 6000, and Mercury devices, see the following documents:

- [ACEX 1K Programmable Logic Device Family Data Sheet](#)
- [APEX 20K Programmable Logic Device Family Data Sheet](#)
- [FLEX 10K Embedded Programmable Logic Family Data Sheet](#)
- [FLEX 10KE Embedded Programmable Logic Family Data Sheet](#)
- [FLEX 8000 Programmable Logic Device Family Data Sheet](#)
- [FLEX 6000 Programmable Logic Device Family Data Sheet](#)
- [Mercury Programmable Logic Device Family Data Sheet](#)

Programming & Configuration File Support

The Quartus and MAX+PLUS II development systems provide programming support for Altera configuration devices. The Quartus and MAX+PLUS II software automatically generates a POF to program each configuration device in a project. In a multi-device project, the software can combine the programming files for multiple ACEX, APEX, FLEX, or Mercury devices into one or more configuration devices. The software allows you to select the appropriate configuration device to most efficiently store the data for each ACEX, APEX, FLEX, and Mercury device. Moreover, when compiling for ACEX 1K, FLEX 10KA, FLEX 10KE, or Mercury devices, the MAX+PLUS II software automatically defaults to generate the EPC1 or EPC1441 POF with the programming bit set for 3.3-V operation.

All Altera configuration devices are programmable using Altera programming hardware in conjunction with the Quartus or MAX+PLUS II software. In addition, many manufacturers offer programming hardware that supports other Altera configuration devices.

The EPC2 configuration device can be programmed in-system through its industry-standard 4-pin JTAG interface. ISP capability in the EPC2 provides ease in prototyping and updating ACEX, APEX, FLEX, and Mercury device functionality. The EPC2 configuration device can be programmed in-system via test equipment using SVF Files, Jam STAPL Files (**.jam**), or Jam STAPL Byte-Code Files (**.jbc**), embedded processors using the Jam programming and test language, and the MAX+PLUS II software via the MasterBlaster, ByteBlasterMV, or BitBlaster download cables. When programming multiple EPC2 devices in a JTAG chain, the Quartus and MAX+PLUS II software and other programming methods employ concurrent programming to simultaneously program multiple devices and reduce programming time. EPC2 devices can be programmed and erased up to 100 times.

After programming an EPC2 device in-system, ACEX, APEX, FLEX, or Mercury device configuration can be initiated by including the EPC2 JTAG configuration instruction. See [Table 8 on page 21](#).



For more information on programming and configuration support, see the following documents:

- [Altera Programming Hardware Data Sheet](#)
- [Programming Hardware Manufacturers](#)
- [MasterBlaster Serial/USB Communications Cable Data Sheet](#)
- [ByteBlasterMV Parallel Port Download Cable Data Sheet](#)
- [ByteBlaster Parallel Port Download Cable Data Sheet](#)
- [BitBlaster Serial Download Cable Data Sheet](#)

IEEE Std. 1149.1 (JTAG) Boundary-Scan Testing

The EPC2 provides JTAG BST circuitry that complies with the IEEE Std. 1149.1-1990 specification. JTAG boundary-scan testing can be performed before or after configuration, but not during configuration. The EPC2 device supports the JTAG instructions shown in [Table 8](#).

The ISP circuitry in EPC2 devices is compatible with tools that support the IEEE Std. 1532. The IEEE Std. 1532 is a standard developed to allow concurrent ISP between multiple PLD vendors.

Table 8. EPC2 JTAG Instructions

JTAG Instruction	Description
SAMPLE/PRELOAD	Allows a snapshot of a signal at the device pins to be captured and examined during normal device operation, and permits an initial data pattern output at the device pins.
EXTEST	Allows the external circuitry and board-level interconnections to be tested by forcing a test pattern at the output pins and capturing results at the input pins.

<i>Table 8. EPC2 JTAG Instructions</i>	
JTAG Instruction	Description
BYPASS	Places the 1-bit bypass register between the TDI and TDO pins, which allows the BST data to pass synchronously through a selected device to adjacent devices during normal device operation.
IDCODE	Selects the device IDCODE register and places it between TDI and TDO, allowing the device IDCODE to be serially shifted out of TDO. The device IDCODE for the EPC2 is shown below: 0000 00010000000000010 00001101110 1
USERCODE	Selects the USERCODE register and places it between TDI and TDO, allowing the USERCODE to be serially shifted out of TDO. The 32-bit USERCODE is a programmable user-defined pattern.
ISP Instructions	These instructions are used when programming an EPC2 device via JTAG ports with a MasterBlaster, ByteBlaster MV, ByteBlaster, or BitBlaster download cable, or using a Jam STAPL File (.jam), Jam STAPL Byte-Code File (.jbc), or SVF File via an embedded processor.
INIT_CONF	This function allows the user to initiate the APEX or FLEX configuration process by tying nINIT_CONF to the APEX or FLEX device(s) nCONFIG pin(s). After this instruction is updated, the nINIT_CONF pin is driven low. When the Initiate Configuration instruction is cleared, nINIT_CONF is released, which starts the APEX or FLEX device configuration. This instruction is used by the MAX+PLUS II software, Jam STAPL Files, and JBC Files.



For more information, see [Application Note 39 \(IEEE 1149.1 \(JTAG\) Boundary-Scan Testing in Altera Devices\)](#).

Figure 9 shows the timing requirements for the JTAG signals.

Figure 9. EPC2 JTAG Waveforms

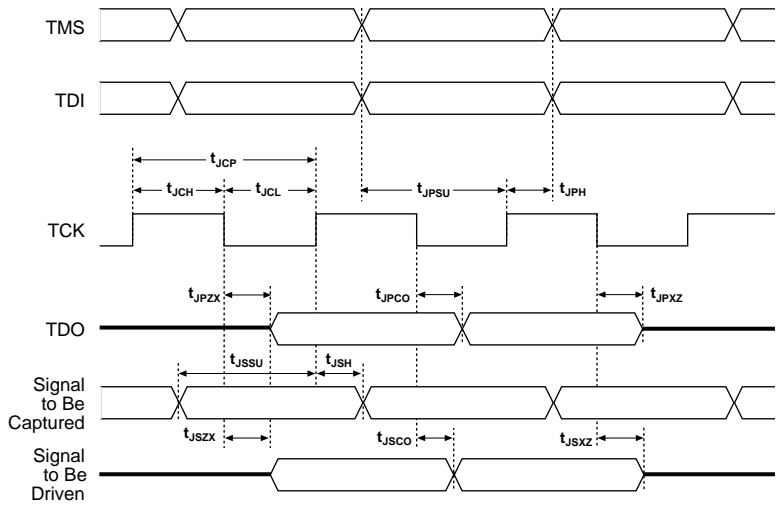


Table 9 shows the timing parameters and values for configuration devices.

Symbol	Parameter	Min	Max	Unit
t_{JCP}	TCK clock period	100		ns
t_{JCH}	TCK clock high time	50		ns
t_{JCL}	TCK clock low time	50		ns
t_{JPSU}	JTAG port setup time	20		ns
t_{JPH}	JTAG port hold time	45		ns
t_{JPCO}	JTAG port clock to output		25	ns
t_{JPZX}	JTAG port high impedance to valid output		25	ns
t_{JPXZ}	JTAG port valid output to high impedance		25	ns
t_{JSSU}	Capture register setup time	20		ns
t_{JSH}	Capture register hold time	45		ns
t_{JSCO}	Update register clock to output		25	ns
t_{JSZX}	Update register high-impedance to valid output		25	ns
t_{JSXZ}	Update register valid output to high impedance		25	ns

Operating Conditions

Tables 10 through 17 provide information on absolute maximum ratings, recommended operating conditions, DC operating conditions, and capacitance for configuration devices.

Table 10. Absolute Maximum Ratings Note (1)

Symbol	Parameter	Conditions	Min	Max	Unit
V_{CC}	Supply voltage	With respect to ground (2)	-2.0	7.0	V
V_I	DC input voltage	With respect to ground (2)	-2.0	7.0	V
I_{MAX}	DC V_{CC} or ground current			50	mA
I_{OUT}	DC output current, per pin		-25	25	mA
P_D	Power dissipation			250	mW
T_{STG}	Storage temperature	No bias	-65	150	°C
T_{AMB}	Ambient temperature	Under bias	-65	135	°C
T_J	Junction temperature	Under bias		135	°C

Table 11. Recommended Operating Conditions

Symbol	Parameter	Conditions	Min	Max	Unit
V_{CC}	Supply voltage for 5.0-V operation	(3), (4)	4.75 (4.50)	5.25 (5.50)	V
	Supply voltage for 3.3-V operation	(3), (4)	3.0 (3.0)	3.6 (3.6)	V
V_I	Input voltage	With respect to ground	-0.3	$V_{CC} + 0.3$ (5)	V
V_O	Output voltage		0	V_{CC}	V
T_A	Operating temperature	For commercial use	0	70	°C
		For industrial use	-40	85	°C
t_R	Input rise time			20	ns
t_F	Input fall time			20	ns

Table 12. DC Operating Conditions

Symbol	Parameter	Conditions	Min	Max	Unit
V_{IH}	High-level input voltage		2.0	$V_{CC} + 0.3$ (5)	V
V_{IL}	Low-level input voltage		-0.3	0.8	V
V_{OH}	5.0-V mode high-level TTL output voltage	$I_{OH} = -4$ mA DC (6)	2.4		V
	3.3-V mode high-level CMOS output voltage	$I_{OH} = -0.1$ mA DC (6)	$V_{CC} - 0.2$		V
V_{OL}	Low-level output voltage	$I_{OL} = 4$ mA DC (6)		0.4	V
I_I	Input leakage current	$V_I = V_{CC}$ or ground	-10	10	μA
I_{OZ}	Tri-state output off-state current	$V_O = V_{CC}$ or ground	-10	10	μA

Table 13. EPC1213, EPC1064 & EPC1064V Device I_{CC} Supply Current Values

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I_{CC0}	V_{CC} supply current (standby)			100	200	μA
I_{CC1}	V_{CC} supply current (during configuration)			10	50	mA

Table 14. EPC2 Device I_{CC} Supply Current Values

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I_{CC0}	V_{CC} supply current (standby)	$V_{CC} = 5.0 \text{ V}$ or 3.3 V		50	100	μA
I_{CC1}	V_{CC} supply current (during configuration)	$V_{CC} = 5.0 \text{ V}$ or 3.3 V		18	50	mA

Table 15. EPC1 Device I_{CC} Supply Current Values

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I_{CC0}	V_{CC} supply current (standby)			50	100	μA
I_{CC1}	V_{CC} supply current (during configuration)	$V_{CC} = 5.0 \text{ V}$		30	50	mA
		$V_{CC} = 3.3 \text{ V}$		10	16.5	mA

Table 16. EPC1441 Device I_{CC} Supply Current Values

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I_{CC0}	V_{CC} supply current (standby)			30	60	μA
I_{CC1}	V_{CC} supply current (during configuration)	$V_{CC} = 5.0 \text{ V}$		15	30	mA
I_{CC1}	V_{CC} supply current (during configuration)	$V_{CC} = 3.3 \text{ V}$		5	10	mA

Table 17. Capacitance *Note (7)*

Symbol	Parameter	Conditions	Min	Max	Unit
C_{IN}	Input pin capacitance	$V_{IN} = 0 \text{ V}$, $f = 1.0 \text{ MHz}$		10	pF
C_{OUT}	Output pin capacitance	$V_{OUT} = 0 \text{ V}$, $f = 1.0 \text{ MHz}$		10	pF

Notes to tables:

- (1) See the *Operating Requirements for Altera Devices Data Sheet* in this data book.
- (2) The minimum DC input is -0.3 V . During transitions, the inputs may undershoot to -2.0 V or overshoot to 7.0 V for input currents less than 100 mA and periods shorter than 20 ns under no-load conditions.
- (3) Numbers in parentheses are for industrial-temperature-range devices.
- (4) Maximum V_{CC} rise time is 100 ms .
- (5) Certain EPC2 pins may be driven to 5.75 V when operated with a $3.3\text{-V } V_{CC}$. See [Table 7 on page 19](#).
- (6) The I_{OH} parameter refers to high-level TTL or CMOS output current; the I_{OL} parameter refers to low-level TTL or CMOS output current.
- (7) Capacitance is sample-tested only.

Tables 18 through 22 show the device configuration parameters for FLEX 10K, FLEX 8000, and FLEX 6000 devices.

Table 18. ACEX 1K, FLEX 10K & FLEX 6000 Device Configuration Parameters Using EPC2 Devices at 5.0-V

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
t _{CE}	OE high to first clock delay				200	ns
t _{OEZX}	OE high to data output enabled				50	ns
t _{CO}	DCLK to data out delay				20	ns
t _{MCH}	DCLK high time for the first device in the configuration chain		30	50	75	ns
t _{MCL}	DCLK low time for the first device in the configuration chain		30	50	75	ns
f _{CK}	Clock frequency		6.7	10	16.7	MHz
t _{SCH}	DCLK high time for subsequent devices		30			ns
t _{SCL}	DCLK low time for subsequent devices		30			ns
t _{CASC}	CLK rising edge to nCASC				20	ns
t _{CCA}	nCS to nCASC cascade delay				10	ns
f _{CDOE}	CLK to data enable/disable				20	ns
t _{OEC}	OE low to CLK disable delay				20	ns
t _{NRCAS}	OE low (reset) to nCASC delay				25	ns
t _{NRR}	OE low time (reset) minimum		100			ns

Table 19. ACEX 1K, APEX 20K, FLEX 10K & Mercury Device Configuration Parameters Using EPC2 Devices at 3.3-V

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
t _{CE}	OE high to first clock delay				300	ns
t _{OEZX}	OE high to data output enabled				80	ns
t _{CO}	DCLK to data out delay				30	ns
t _{MCH}	DCLK high time for the first device in the configuration chain		40	65	100	ns
t _{MCL}	DCLK low time for the first device in the configuration chain		40	65	100	ns
f _{CK}	Clock frequency		5	7.7	12.5	MHz
t _{SCH}	DCLK high time for subsequent devices		40			ns
t _{SCL}	DCLK low time for subsequent devices		40			ns
t _{CASC}	CLK rising edge to nCASC				25	ns
t _{CCA}	nCS to nCASC cascade delay				15	ns
f _{CDOE}	CLK to data enable/disable				30	ns
t _{OEC}	OE low to CLK disable delay				30	ns
t _{NRCAS}	OE low (reset) to nCASC delay				30	ns
t _{NRR}	OE low time (reset) minimum		100			ns

Table 20. ACEX 1K, FLEX 10K & FLEX 6000 Device Configuration Parameters Using EPC1 & EPC1441 Devices at 5.0-V

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
t_{CE}	OE high to first clock delay				200	ns
t_{OEZX}	OE high to data output enabled				50	ns
t_{CO}	DCLK to data out delay				20	ns
t_{MCH}	DCLK high time for the first device in the configuration chain		30	50	75	ns
t_{MCL}	DCLK low time for the first device in the configuration chain		30	50	75	ns
f_{CK}	Clock frequency		6.7	10	16.7	MHz
t_{SCH}	DCLK high time for subsequent devices		30			ns
t_{SCL}	DCLK low time for subsequent devices		30			ns
t_{CASC}	CLK rising edge to nCASC				20	ns
t_{CCA}	nCS to nCASC cascade delay				10	ns
f_{CDOE}	CLK to data enable/disable				20	ns
t_{OEC}	OE low to CLK disable delay				20	ns
t_{NRCAS}	OE low (reset) to nCASC delay				25	ns
t_{NRR}	OE low time (reset) minimum		100			ns

Table 21. ACEX 1K, FLEX 10K & FLEX 6000 Device Configuration Parameters Using EPC1 & EPC1441 Devices at 3.3-V

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
t_{CE}	OE high to first clock delay				300	ns
t_{OEZX}	OE high to data output enabled				80	ns
t_{CO}	DCLK to data out delay				30	ns
t_{MCH}	DCLK high time for the first device in the configuration chain		50	125	250	ns
t_{MCL}	DCLK low time for the first device in the configuration chain		50	125	250	ns
f_{CK}	Clock frequency		2	4	10	MHz
t_{SCH}	DCLK high time for subsequent devices		50			ns
t_{SCL}	DCLK low time for subsequent devices		50			ns
t_{CASC}	CLK rising edge to nCASC				25	ns
t_{CCA}	nCS to nCASC cascade delay				15	ns
f_{CDOE}	CLK to data enable/disable				30	ns
t_{OEC}	OE low to CLK disable delay				30	ns
t_{NRCAS}	OE low (reset) to nCASC delay				30	ns
t_{NRR}	OE low time (reset) minimum		100			ns

Table 22. FLEX 8000 Device Configuration Parameters Using EPC1, EPC1441, EPC1213, EPC1064 & EPC1064V Devices

Symbol	Parameter	Conditions	EPC1064V		EPC1064 EPC1213		EPC1 EPC1441		Unit
			Min	Max	Min	Max	Min	Max	
t _{OEZX}	OE high to DATA output enabled			75		50		50	ns
t _{CSZX}	nCS low to DATA output enabled			75		50		50	ns
t _{CSXZ}	nCS high to DATA output disabled			75		50		50	ns
t _{CSS}	nCS low setup time to first DCLK rising edge		150		100		50		ns
t _{CSH}	nCS low hold time after DCLK rising edge		0		0		0		ns
t _{DSU}	Data setup time before rising edge on DCLK		75		50		50		ns
t _{DH}	Data hold time after rising edge on DCLK		0		0		0		ns
t _{CO}	DCLK to DATA out delay			100		75		75	ns
t _{CK}	Clock period		240		160		100		ns
f _{CK}	Clock frequency			4		6		8	MHz
t _{CL}	DCLK low time		120		80		50		ns
t _{CH}	DCLK high time		120		80		50		ns
t _{XZ}	OE low or nCS high to DATA output disabled			75		50		50	ns
t _{OEW}	OE pulse width to guarantee counter reset		150		100		100		ns
t _{CASC}	Last DCLK + 1 to nCASC low delay			90		60		50	ns
t _{CKXZ}	Last DCLK + 1 to DATA tri-state delay			75		50		50	ns
t _{CEOUT}	nCS high to nCASC high delay			150		100		100	ns



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