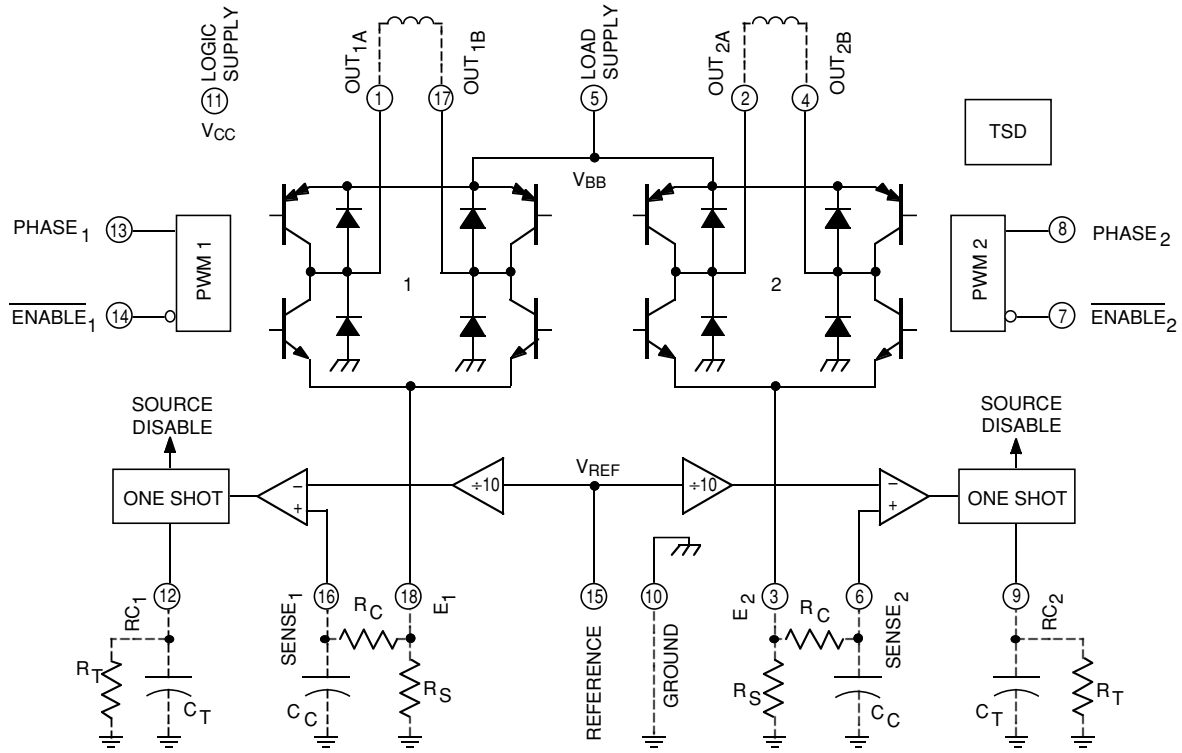


2918 DUAL FULL-BRIDGE PWM MOTOR DRIVER

FUNCTIONAL BLOCK DIAGRAM



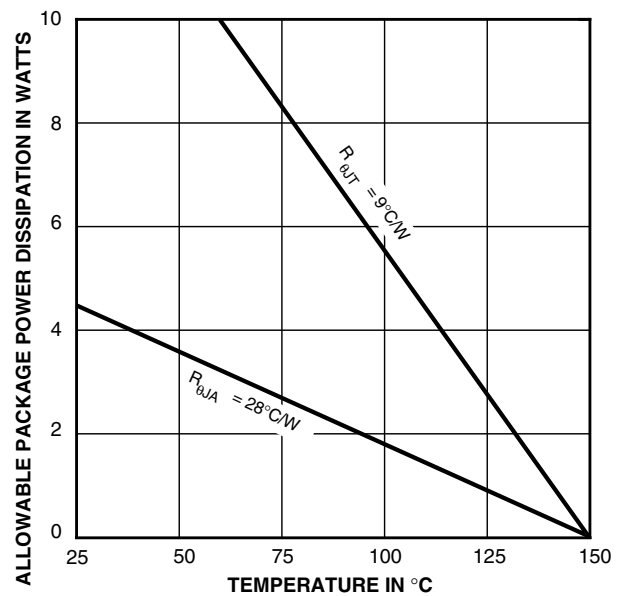
Dwg. FP-033

TRUTH TABLE

Enable	Phase	Out _A	Out _B
L	H	H	L
L	L	L	H
H	X	Z	Z

X = Don't care

Z = High impedance



Dwg. GP-043



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ELECTRICAL CHARACTERISTICS at $T_A = +25^\circ\text{C}$, $V_{BB} = 45\text{ V}$, $V_{CC} = 4.75\text{ V to }5.25\text{ V}$, $V_{REF} = 5.0\text{ V}$ (unless otherwise noted).

Characteristic	Symbol	Test Conditions	Limits			
			Min.	Typ.	Max.	Units
Output Drivers (OUT_A or OUT_B)						
Motor Supply Range	V_{BB}		10	—	45	V
Output Leakage Current	I_{CEX}	$V_{OUT} = V_{BB}$	—	<1.0	50	μA
		$V_{OUT} = 0$	—	<-1.0	-50	μA
Output Sustaining Voltage	$V_{CE(sus)}$	$I_{OUT} = \pm 1.5\text{ A}$, $L = 3.0\text{ mH}$	45	—	—	V
Output Saturation Voltage	$V_{CE(SAT)}$	Sink Driver, $I_{OUT} = +1.0\text{ A}$	—	0.7	0.8	V
		Sink Driver, $I_{OUT} = +1.5\text{ A}$	—	0.9	1.1	V
		Source Driver, $I_{OUT} = -1.0\text{ A}$	—	1.8	2.0	V
		Source Driver, $I_{OUT} = -1.5\text{ A}$	—	1.9	2.2	V
Clamp Diode Leakage Current	I_R	$V_R = 45\text{ V}$	—	<1.0	50	μA
Clamp Diode Forward Voltage	V_F	$I_F = 1.5\text{ A}$	—	1.6	2.0	V
Driver Supply Current	$I_{BB(ON)}$	Both Bridges ON, No Load	—	12	15	mA
	$I_{BB(OFF)}$	Both Bridges OFF	—	8.0	10	mA

Control Logic

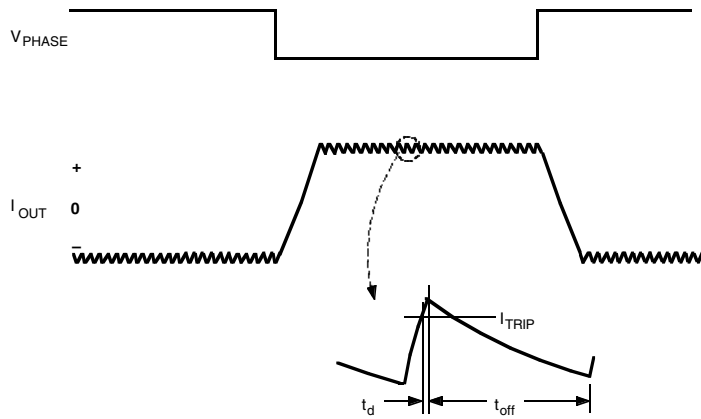
Input Voltage	$V_{IN(1)}$	All Inputs	2.4	—	—	V
	$V_{IN(0)}$	All Inputs	—	—	0.8	V
Input Current	$I_{IN(1)}$	$V_{IN} = 2.4\text{ V}$	—	<1.0	20	μA
	$I_{IN(0)}$	$V_{IN} = 0.8\text{ V}$	—	-3.0	-200	μA
Reference Voltage Range	V_{REF}	Operating	1.5	—	V_{CC}	V
Current Limit Threshold	V_{REF}/V_{SENSE}	At Trip Point	9.5	10	10.5	—
Thermal Shutdown Temp.	T_J		—	170	—	$^\circ\text{C}$
Total Logic Supply Current	$I_{CC(ON)}$	$V_{EN} = 0.8\text{ V}$, No Load	—	105	140	mA
	$I_{CC(OFF)}$	$V_{EN} = 2.4\text{ V}$, No Load	—	10	12	mA

Negative current is defined as coming out of (sourcing) the specified device pin.

Typical Data is for design information only.

2918 DUAL FULL-BRIDGE PWM MOTOR DRIVER

PWM OUTPUT CURRENT WAVEFORM



Dwg. WM-003-1A

APPLICATIONS INFORMATION

PWM Current Control

The A2918SWH/V dual bridges are designed to drive both windings of a bipolar stepper motor. Output current is sensed and controlled independently in each bridge by an external sense resistor (R_S), an internal comparator, and an internal monostable multivibrator.

When the bridge is turned ON, current increases in the motor winding and it is sensed by R_S until the sense voltage (V_{SENSE}) reaches the level set at the comparator's input:

$$I_{TRIP} = V_{REF}/10 R_S$$

The comparator then triggers the monostable which turns OFF the source driver of the bridge. The actual load current peak will be slightly higher than the trip point (especially for low-inductance loads) because of internal logic and switching delays. This delay (t_d) is 2 μ s typically. After turn-off, the motor current decays, circulating through the ground clamp diode and sink transistor. The source driver's OFF time t_{off} , and therefore the magnitude of the current decrease, is determined by the monostable's external RC timing components, where $t_{off} = R_T C_T$ within the range of 20 k Ω to 100 k Ω and 200 pF to 500 pF.

When the source driver is re-enabled, the winding current (the sense voltage) again is allowed to rise to the comparator's threshold. This cycle repeats itself, maintaining the average motor winding current at the desired level.

Special circuitry has been included to prevent runaway current control when t_{off} is set too short. This circuitry prevents the source driver from being re-enabled until the load current has decayed to below the I_{TRIP} level.

Loads with high distributed capacitances may result in high turn-ON current peaks. This peak, appearing across R_S , will attempt to trip the comparator, resulting in possible erroneous current control or high-frequency oscillations. An external $R_C C_C$ low-pass filter may be used to delay the action of the comparator, and thus ignore turn-on spikes.

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General

To avoid excessive voltage spikes on the LOAD SUPPLY pin (V_{BB}), a large-value capacitor ($\geq 47 \mu\text{F}$) should be connected from V_{BB} to the ground pin as close as possible to the device. Under no circumstances should the voltage at V_{BB} exceed 45 V.

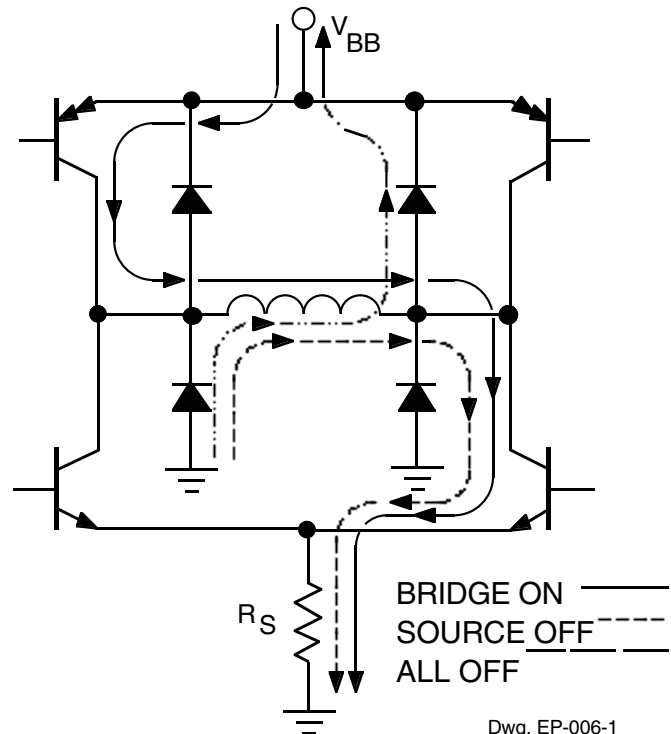
The PHASE input to each bridge determines the direction motor winding current flows. An internally generated deadtime, of approximately $3 \mu\text{s}$, prevents crossover currents that can occur when switching the PHASE input.

All four drivers in the bridge output can be turned OFF, with $V_{EN} \geq 2.4$, resulting in a fast current decay through the internal ground clamp and flyback diodes. The fast current decay is desirable in half-step and high-speed applications. The ENABLE input must be tied low if it is not used.

Varying the reference voltage (V_{REF}) provides continuous control of the peak load current.

Thermal protection circuitry turns OFF all drivers when the junction temperature reaches approximately $+170^\circ\text{C}$. It is intended only to protect the device from failures due to excessive junction temperature and should not imply that output short circuits are permitted. The output drivers are re-enabled when the junction temperature cools to approximately $+145^\circ\text{C}$.

LOAD CURRENT PATHS



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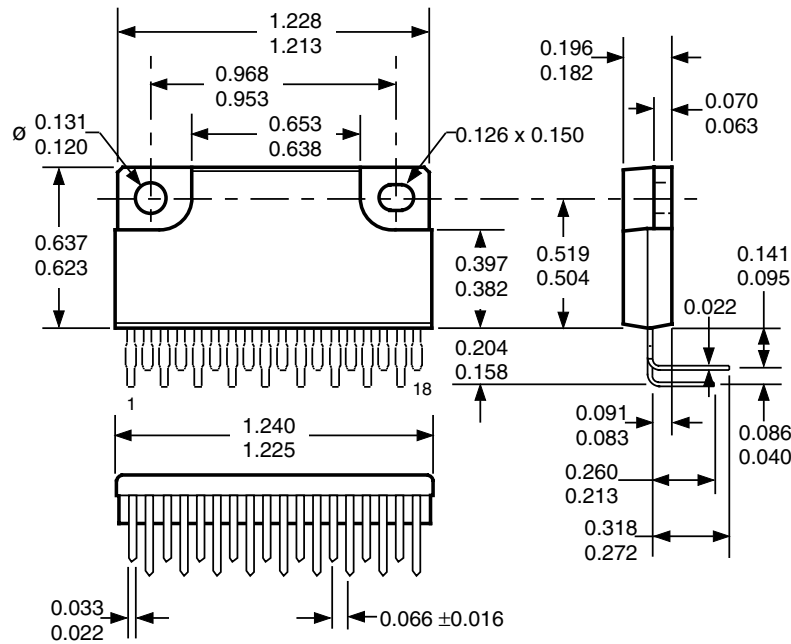
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2918 DUAL FULL-BRIDGE PWM MOTOR DRIVER

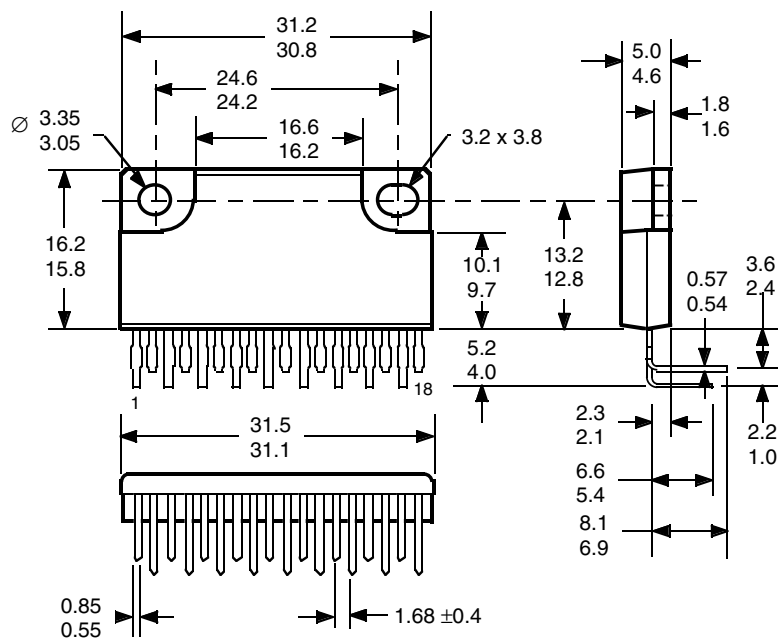
A2918SWH for horizontal mounting

Dimensions in Inches
(for reference only)



Dimensions in Millimeters
(controlling dimensions)

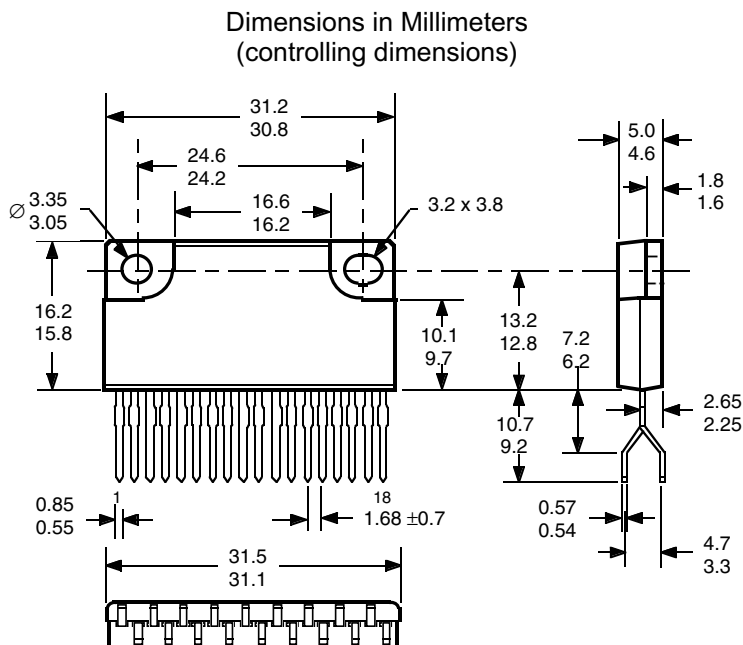
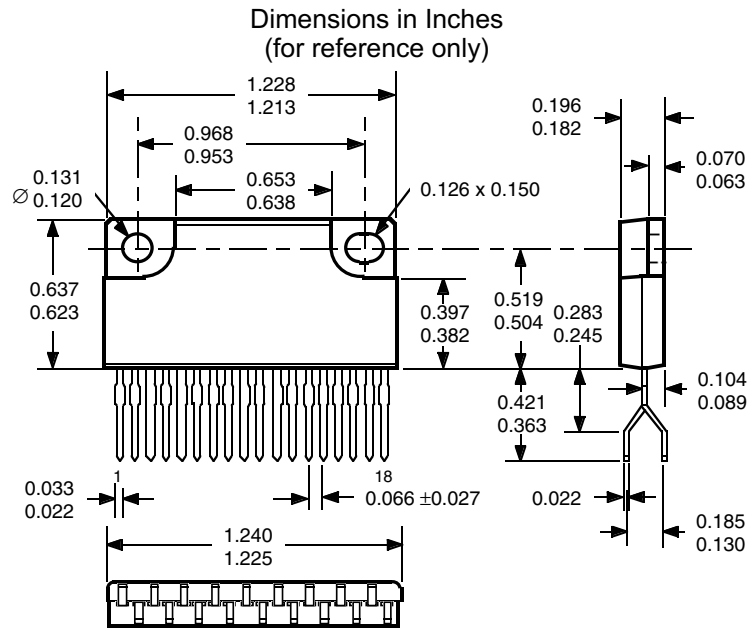
Dwg. MP-006 in



- NOTES: 1. Exact body and lead configuration at vendor's option within limits shown. Dwg. MP-006 mm
2. Lead spacing tolerance is non-cumulative.

2918 DUAL FULL-BRIDGE PWM MOTOR DRIVER

A2918SWV for vertical mounting



- NOTES: 1. Exact body and lead configuration at vendor's option within limits shown.
2. Lead spacing tolerance is non-cumulative.

2918 DUAL FULL-BRIDGE PWM MOTOR DRIVER

MOTOR DRIVERS

Function	Output Ratings*		Part Number†
INTEGRATED CIRCUITS FOR BRUSHLESS DC MOTORS			
3-Phase Power MOSFET Controller	—	28 V	3933
3-Phase Power MOSFET Controller	—	50 V	3932
3-Phase Power MOSFET Controller	—	50 V	7600
2-Phase Hall-Effect Sensor/Driver	400 mA	26 V	3626
Bidirectional 3-Phase Back-EMF Controller/Driver	±600 mA	14 V	8906
2-Phase Hall-Effect Sensor/Driver	900 mA	14 V	3625
3-Phase Back-EMF Controller/Driver	±900 mA	14 V	8902–A
3-Phase Controller/Drivers	±2.0 A	45 V	2936 & 2936-120
INTEGRATED BRIDGE DRIVERS FOR DC AND BIPOLAR STEPPER MOTORS			
Dual Full Bridge with Protection & Diagnostics	±500 mA	30 V	3976
PWM Current-Controlled Dual Full Bridge	±650 mA	30 V	3966
PWM Current-Controlled Dual Full Bridge	±650 mA	30 V	3968
PWM Current-Controlled Dual Full Bridge	±750 mA	45 V	2916
PWM Current-Controlled Dual Full Bridge	±750 mA	45 V	2919
PWM Current-Controlled Dual Full Bridge	±750 mA	45 V	6219
PWM Current-Controlled Dual Full Bridge	±800 mA	33 V	3964
PWM Current-Controlled Full Bridge	±1.3 A	50 V	3953
PWM Current-Controlled Dual Full Bridge	±1.5 A	45 V	2917
PWM Current-Controlled Microstepping Full Bridge	±1.5 A	50 V	3955
PWM Current-Controlled Microstepping Full Bridge	±1.5 A	50 V	3957
PWM Current-Controlled Dual DMOS Full Bridge	±1.5 A	50 V	3972
Dual Full-Bridge Driver	±2.0 A	50 V	2998
PWM Current-Controlled Full Bridge	±2.0 A	50 V	3952
DMOS Full Bridge PWM Driver	±2.0 A	50 V	3958
Dual DMOS Full Bridge	±2.5 A	50 V	3971
UNIPOLAR STEPPER MOTOR & OTHER DRIVERS			
Voice-Coil Motor Driver	±500 mA	6 V	8932–A
Voice-Coil Motor Driver	±800 mA	16 V	8958
Unipolar Stepper-Motor Quad Drivers	1 A	46 V	7024 & 7029
Unipolar Microstepper-Motor Quad Driver	1.2 A	46 V	7042
Unipolar Stepper-Motor Translator/Driver	1.25 A	50 V	5804
Unipolar Stepper-Motor Quad Driver	1.8 A	50 V	2540
Unipolar Stepper-Motor Quad Driver	1.8 A	50 V	2544
Unipolar Stepper-Motor Quad Driver	3 A	46 V	7026
Unipolar Microstepper-Motor Quad Driver	3 A	46 V	7044

* Current is maximum specified test condition, voltage is maximum rating. See specification for sustaining voltage limits or over-current protection voltage limits. Negative current is defined as coming out of (sourcing) the output.

† Complete part number includes additional characters to indicate operating temperature range and package style.

Also, see 3175, 3177, 3235, and 3275 Hall-effect sensors for use with brushless dc motors.

