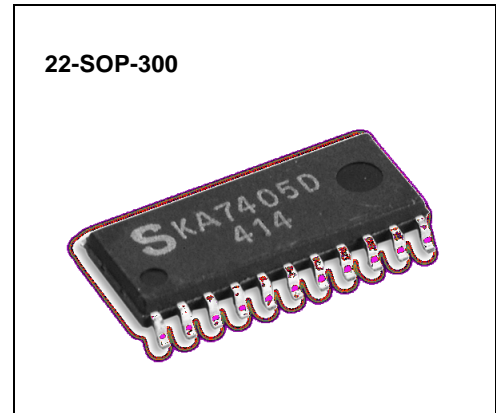


### ZOOM & REEL MOTOR DRIVER

The KA7405D is a monolithic integrated circuit, and suitable for the zoom & reel motor driver for camera, tape deck, any other consumer and industrial applications.

### FEATURES

- Output current up to 1.5A (Each channel).
- 4 function mode (CW, CCW, STOP and BRAKE) are controlled by 2 logic circuits.
- Operating voltage range:  $V_{CC} = 2.5 \sim 6.0V$ .
- Built-in spike killer diode.
- Low saturation voltage.



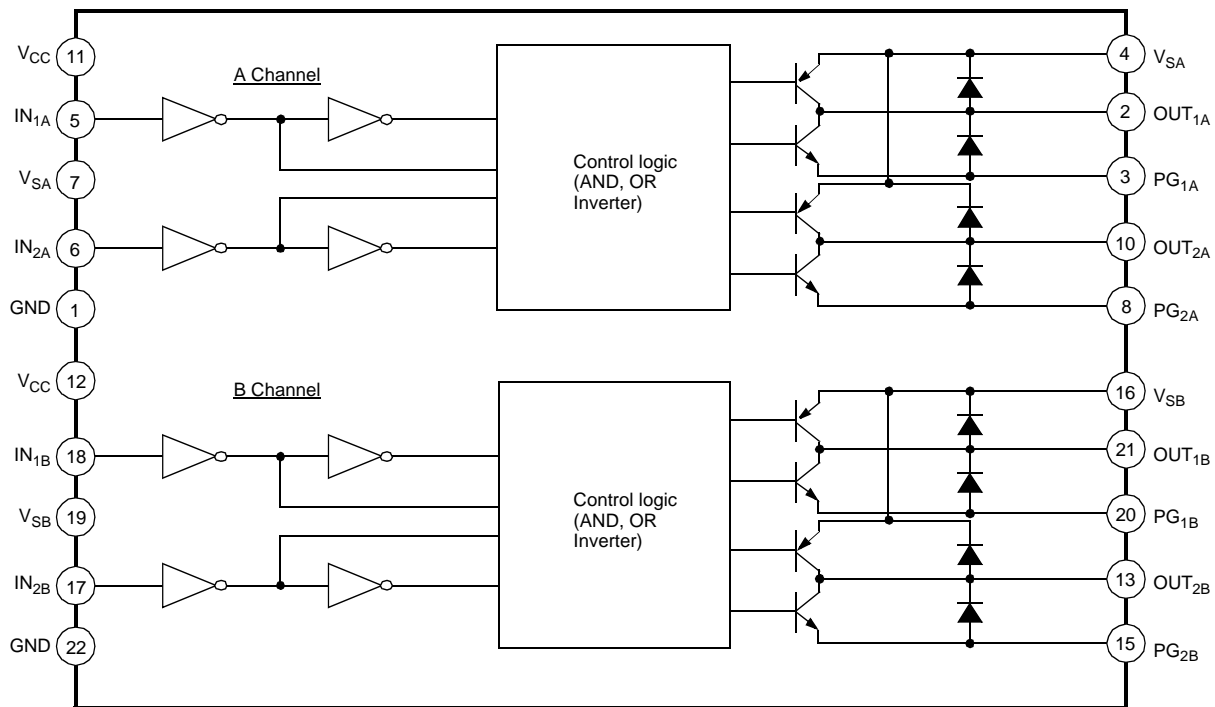
### ORDERING INFORMATION

Device	Package	Operating Temperature
KA7405D	22-SOP-300	-25°C to +75°C

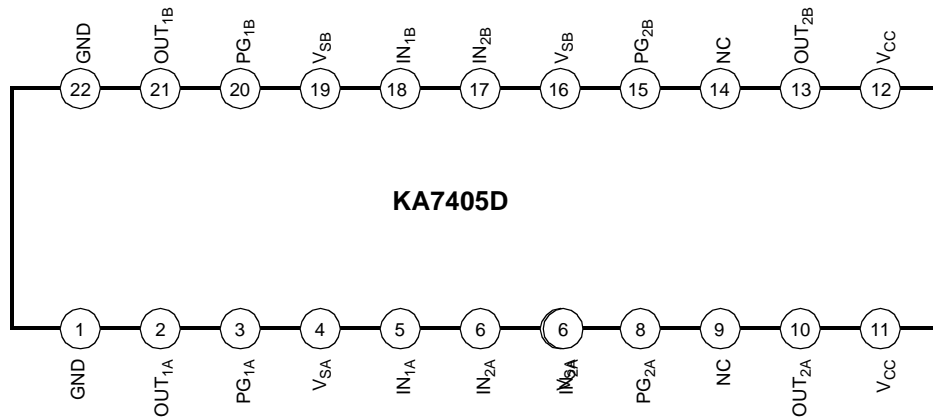
### TARGET APPLICATIONS

- Film & zoom motors for camera system
- A toy or the other DC motors

### BLOCK DIAGRAM



## PIN CONFIGURATIONS



## PIN DESCRIPTIONS

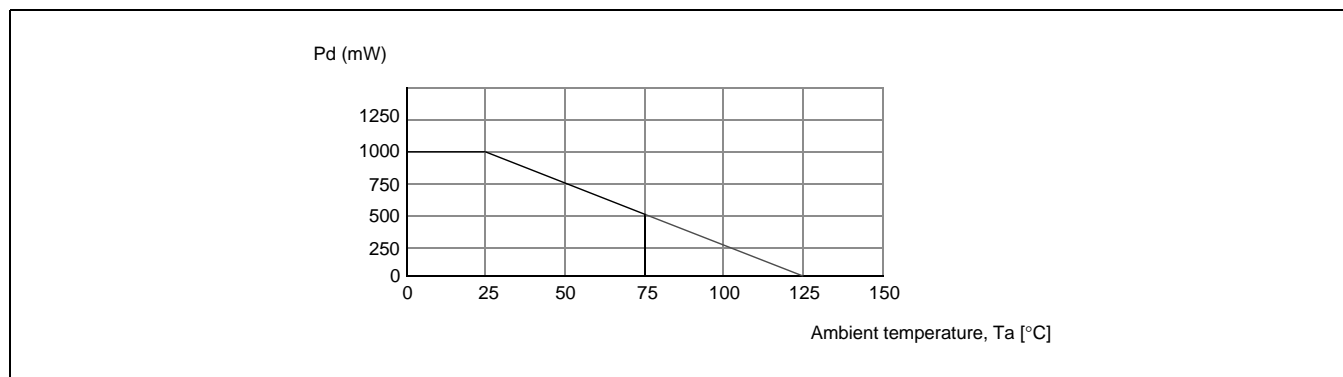
Pin No.	Symbol	I/O	Define	Remark
1	GND	-	Signal ground	-
2	OUT <sub>1A</sub>	O	Output 1	Channel A
3	PG <sub>1A</sub>	-	Power ground 1	Channel A
4	V <sub>SA</sub>	-	Output supply voltage	Channel A
5	IN <sub>1A</sub>	I	Input 1	Channel A
6	IN <sub>2A</sub>	I	Input 2	Channel A
7	V <sub>SA</sub>	-	Output supply voltage	Channel A
8	PG <sub>2A</sub>	-	Power ground 2	Channel A
9	NC	-	No connection	-
10	OUT <sub>2A</sub>	O	Output 2	-
11	V <sub>CC</sub>	-	Supply voltage	-
12	V <sub>CC</sub>	-	Supply voltage	-
13	OUT <sub>2B</sub>	O	Output 2	Channel B
14	NC	-	No connection	-
15	PG <sub>2B</sub>	-	Power ground 2	Channel B
16	V <sub>SB</sub>	-	Output supply voltage	Channel B
17	IN <sub>2B</sub>	I	Input 2	Channel B
18	IN <sub>1B</sub>	I	Input 1	Channel B
19	V <sub>SB</sub>	-	Output supply voltage	Channel B
20	PG <sub>1B</sub>	-	Power ground 1	Channel B
21	OUT <sub>1B</sub>	O	Output 1	Channel B
22	GND	-	Signal ground	-

## EQUIVALENT CIRCUITS

Description	Pin No.	Internal Circuit
Control Input		
IN <sub>1A</sub>	5	
IN <sub>2A</sub>	6	
IN <sub>1B</sub>	18	
IN <sub>2B</sub>	17	
V <sub>CC</sub>	11, 12	
GND	1, 22	
Motor Output		
OUT <sub>1A</sub>	2	
OUT <sub>2A</sub>	10	
OUT <sub>1B</sub>	21	
OUT <sub>2B</sub>	13	
V <sub>SA</sub>	4, 7	
V <sub>SB</sub>	16, 19	
PG <sub>1A</sub>	3	
PG <sub>2A</sub>	8	
PG <sub>1B</sub>	20	
PG <sub>2B</sub>	15	

**ABSOLUTE MAXIMUM RATING (Ta=25°C)**

Characteristics	Symbol	Value	Unit
Power supply voltage	$V_{CCMAX}$	6.0	V
Channel supply voltage	$V_{SMAX}$	6.0	V
Power dissipation	$P_D$	1000	mW
Operating temperature	$T_{OPR}$	-25 ~ +75	°C
Storage temperature	$T_{STG}$	-40 ~ +125	°C
Output current	$I_{OMAX}$	1.5	A

**RECOMMENDED OPERATING CONDITIONS (Ta=25°C)**

Characteristics	Symbol	Min.	Typ.	Max.	Unit
Operating supply voltage	$V_{CC}$	2.5	-	6.0	V

## ELECTRICAL CHARACTERISTICS

(V<sub>CC</sub>=5V, T<sub>a</sub>=25°C, unless otherwise specified)

Characteristic	Symbol	Test conditions	Min.	Typ.	Max.	Unit
Supply current 1	I <sub>CC1</sub>	V <sub>IN</sub> (all) = 0V	–	0.1	10	μA
Supply current 2	I <sub>CC2</sub>	V <sub>IN1</sub> =3V	–	15	30	mA
Supply current 3	I <sub>CC3</sub>	V <sub>IN2</sub> =3V	–	15	30	mA
Supply current 4	I <sub>CC4</sub>	V <sub>IN</sub> =3V	–	30	50	mA
Input current	I <sub>IN</sub>	V <sub>CC</sub> =6V, V <sub>IN</sub> =2V	–	45	80	μA
Leakage current	I <sub>IK</sub>	V <sub>CC</sub> =7V	–	0.1	10	μA
Upper spark diode forward voltage	V <sub>SF1</sub>	I <sub>O</sub> =500mA	–	1.0	1.7	V
Lower spark diode forward voltage	V <sub>SF2</sub>	I <sub>O</sub> =500mA	–	1.0	1.7	V
Output saturation voltage (1A)	V <sub>O1A</sub>	I <sub>OA</sub> =300mA	–	0.45	0.70	V
Output saturation voltage (1B)	V <sub>O1B</sub>	I <sub>OB</sub> =300mA	–	0.45	0.70	V
Output saturation voltage (2A)	V <sub>O2A</sub>	I <sub>OA</sub> =600mA	–	1.0	1.5	V
Output saturation voltage (2B)	V <sub>O2B</sub>	I <sub>OB</sub> =600mA	–	1.0	1.5	V
Output saturation voltage (3A)	V <sub>O3A</sub>	I <sub>OA</sub> =300mA	–	0.45	0.70	V
Output saturation voltage (3B)	V <sub>O3B</sub>	I <sub>OB</sub> =300mA	–	0.45	0.70	V
Output saturation voltage (4A)	V <sub>O4A</sub>	I <sub>OA</sub> =600mA	–	1.0	1.5	V
Output saturation voltage (4B)	V <sub>O4B</sub>	I <sub>OB</sub> =600mA	–	1.0	1.5	V
Output saturation voltage 5	V <sub>O5</sub>	I <sub>O</sub> =600mA	–	0.6	0.8	V
Output saturation voltage 6	V <sub>O6</sub>	I <sub>O</sub> =600mA	–	0.6	0.8	V
Output saturation voltage 7	V <sub>O7</sub>	I <sub>O</sub> =1200mA	–	1.2	1.6	V
Output saturation voltage 8	V <sub>O8</sub>	I <sub>O</sub> =1200mA	–	1.2	1.6	V
Output sustain voltage	V <sub>SUS</sub>	I <sub>O</sub> =500mA	10	15	–	V
Output saturation low voltage A <sup>note</sup>	V <sub>OLA</sub>	V <sub>CC</sub> =1.9V I <sub>OA</sub> =400mA	–	0.45	0.70	V
Output saturation low voltage B <sup>note</sup>	V <sub>OLB</sub>	V <sub>CC</sub> =1.9V I <sub>OA</sub> =400mA	–	0.45	0.70	V

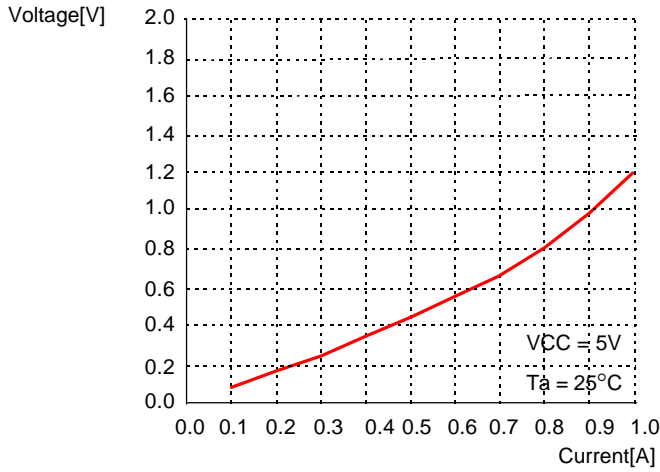
**NOTE:** User's option.

**MOTOR OPERATION TRUTH TABLE**

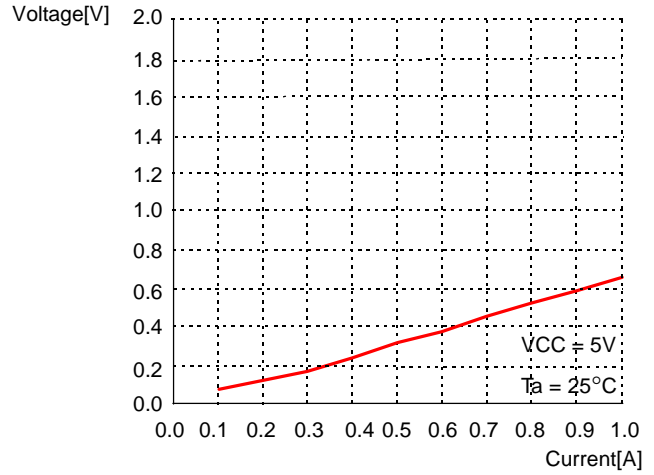
Motor Operation \ Input/Output	Input 1	Input 2	Output 1	Output 2	Remark
Stop	Low	Low	Off	Off	High impedance
Forward Operation	Low	High	Low	High	CW / CCW
Backward Operation	High	Low	High	Low	CCW / CW
Fast stop	High	High	Low	Low	Brake

**ELECTRICAL CHARACTERISTICS CURVES**

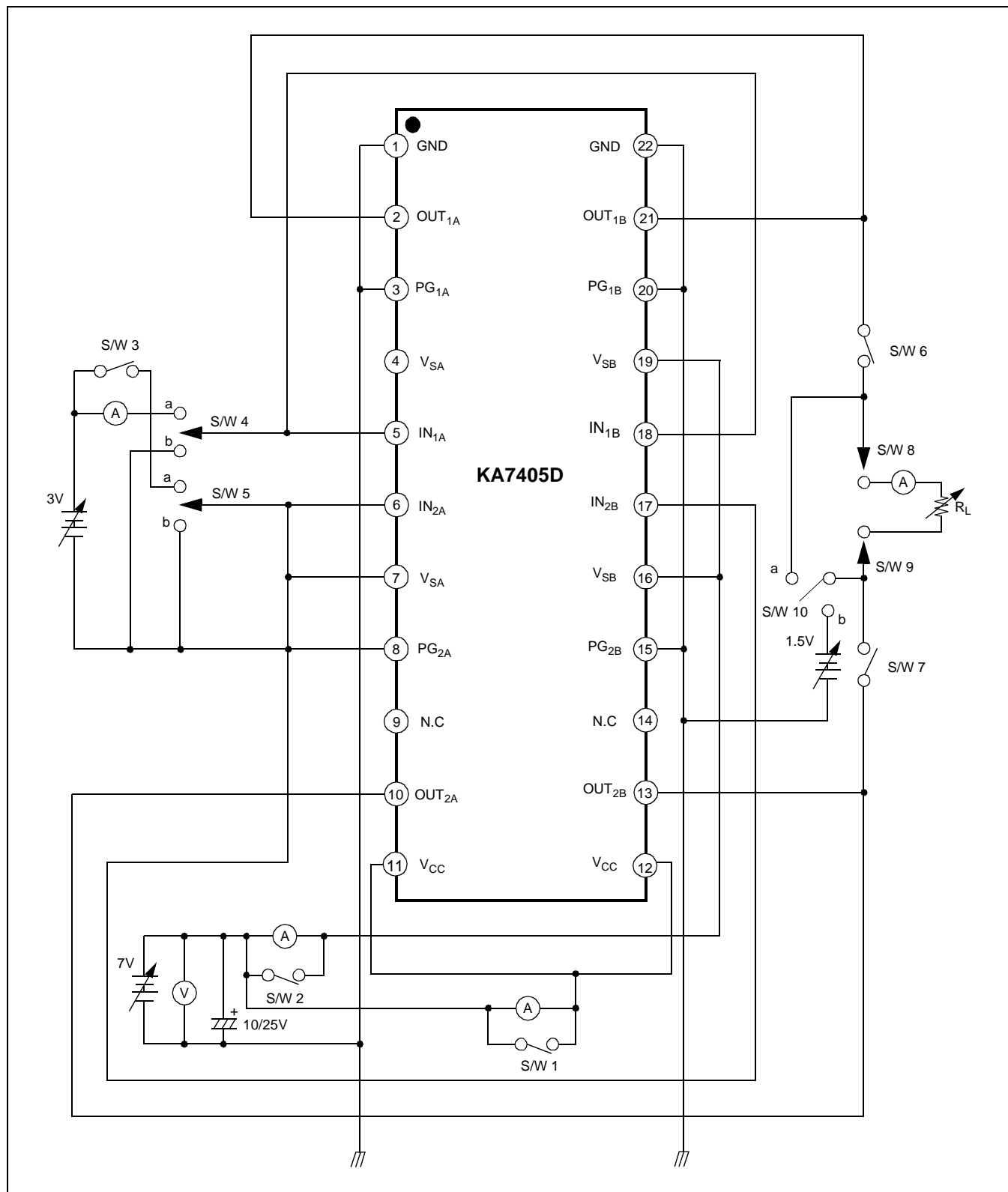
PNP Saturation Voltage



NPN Saturation Voltage



TEST CIRCUIT



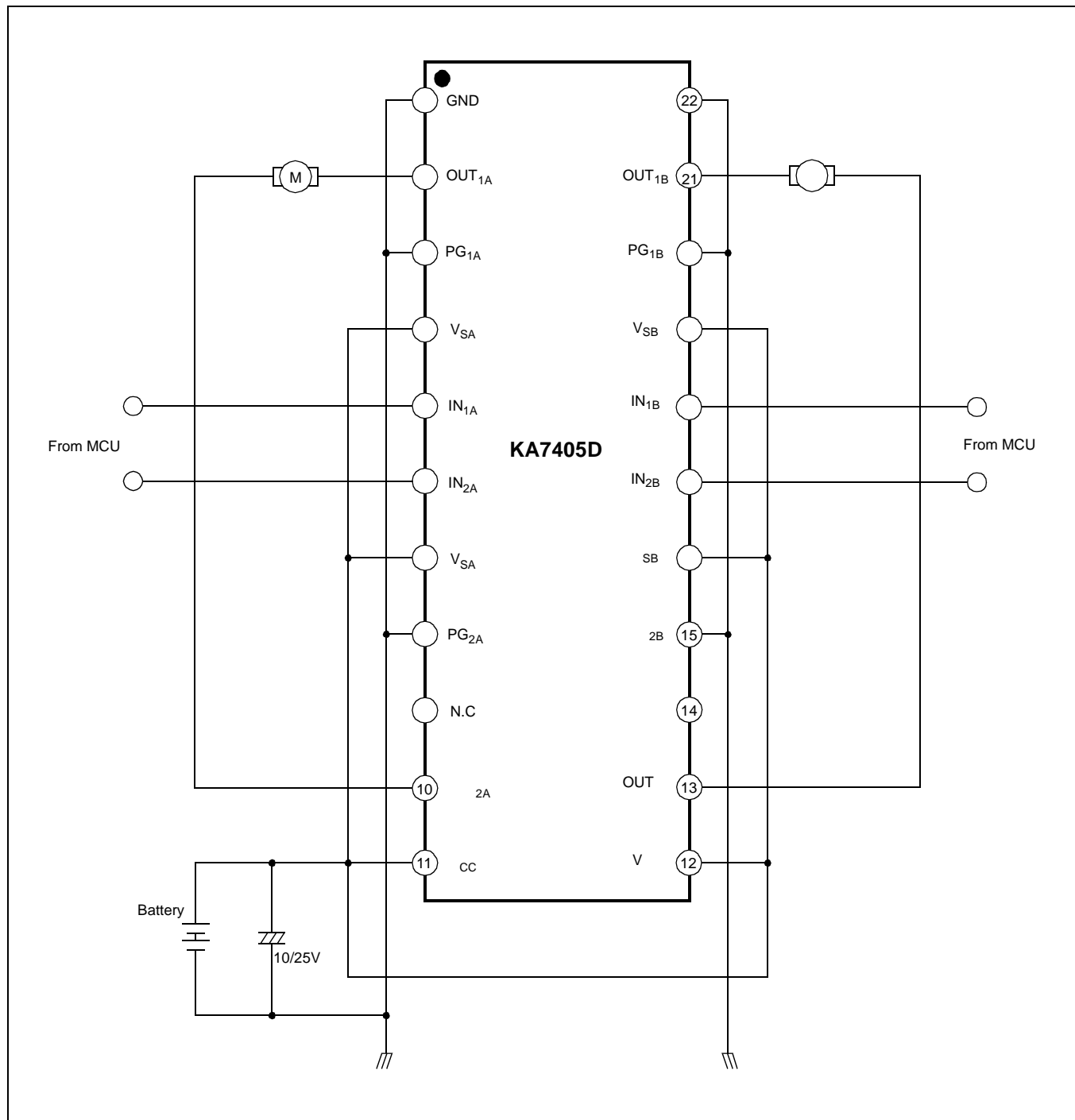
## TEST CONDITIONS

Characteristics	SW1	SW2	SW3	SW4	SW5	SW6	SW7	SW8	SW9	SW10	Remark
$I_{CC1}$	Off	Off	X	b	b	Off	Off	X	X	Off	Supply current
$I_{CC2}$	Off	Off	On	a	b	Off	Off	X	X	Off	Supply current
$I_{CC3}$	Off	Off	On	b	a	Off	Off	X	X	Off	Supply current
$I_{CC4}$	Off	Off	On	a	a	Off	Off	X	X	Off	Supply current
$I_{IN}$	On	On	On	a	a	Off	Off	X	X	Off	Input current
$I_{IK}$	Off	Off	Off	b	b	Off	Off	X	X	Off	Leakage current
$V_{SF1}$	On	On	On	a	b	On	On	Off	Off	a	Spark diode
$V_{SF2}$	On	On	On	b	a	On	On	Off	Off	b	Spark diode
$V_{O1A}$	On	On	On	a	b	On	On	On	On	Off	Single mode
$V_{O2A}$	On	On	On	b	a	On	On	On	On	Off	Single mode
$V_{O3A}$	On	On	On	a	b	On	On	On	On	Off	Single mode
$V_{O4A}$	On	On	On	b	a	On	On	On	On	Off	Single mode
$V_{O5}$	On	On	On	a	b	On	On	On	On	Off	Parallel mode
$V_{O6}$	On	On	On	b	a	On	On	On	On	Off	Parallel mode
$V_{O7}$	On	On	On	a	b	On	On	On	On	Off	Parallel mode
$V_{O8}$	On	On	On	b	a	On	On	On	On	Off	Parallel mode
$V_{SUS}$	Off	Off	X	b	b	On	On	On	On	Off	Sustain voltage

**NOTE:** 'X': Don't care.

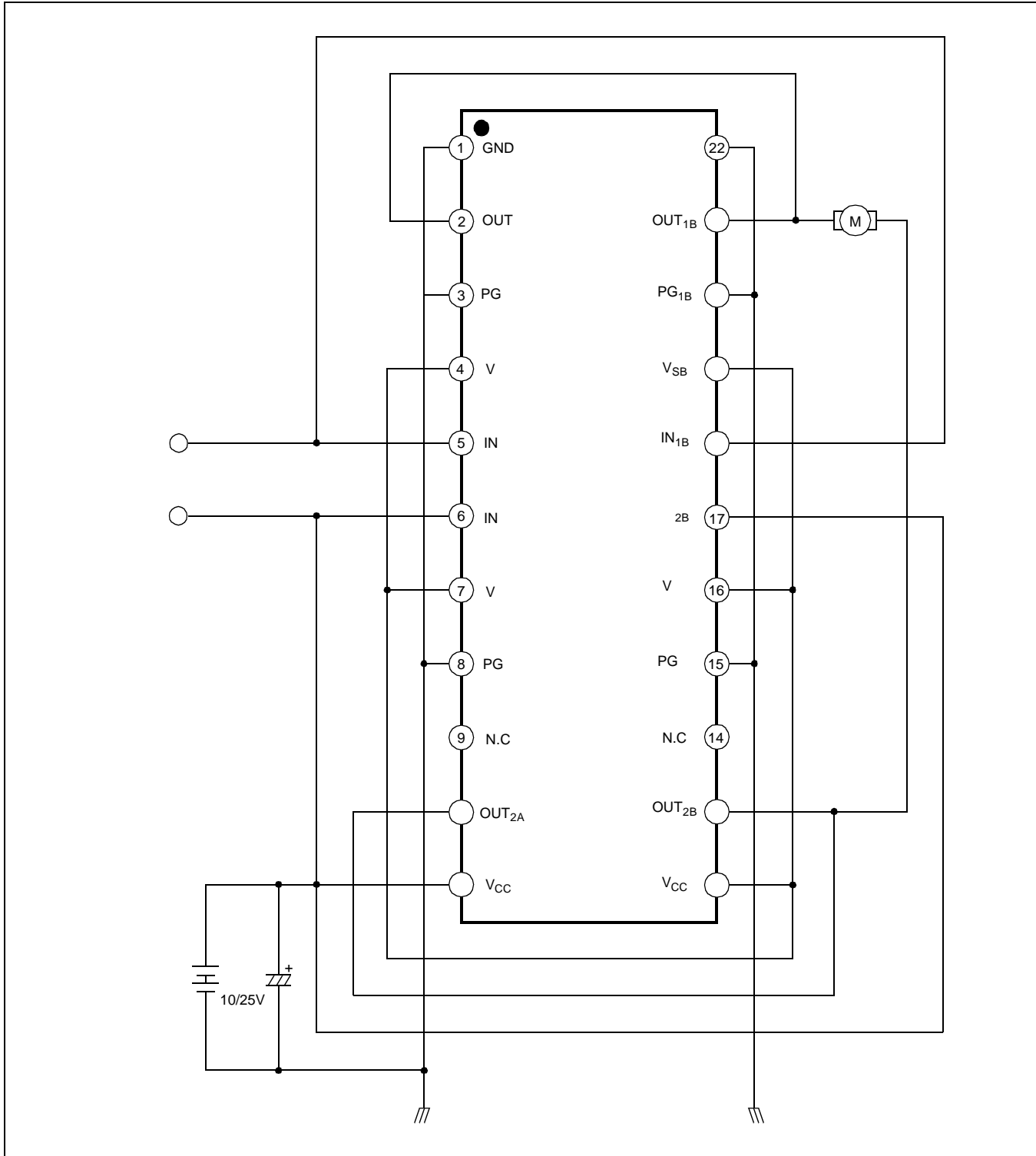
APPLICATION CIRCUIT 1

(Single drive mode)



### APPLICATION CIRCUIT 2

(Parallel drive mode)





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