

## LOW VOLTAGE 512K (64K x 8) OTP ROM

- LOW VOLTAGE READ OPERATION:  
3V to 5.5V
- ACCESS TIME: 120, 150 and 200ns
- LOW POWER "CMOS" CONSUMPTION:
  - Active Current 10mA
  - Standby Current 10 $\mu$ A
- PROGRAMMING VOLTAGE: 12.75V
- PROGRAMMING TIMES of AROUND 6sec.  
(PRESTO IIB ALGORITHM)
- M27V512 is PROGRAMMABLE as M27C512  
with IDENTICAL SIGNATURE

### DESCRIPTION

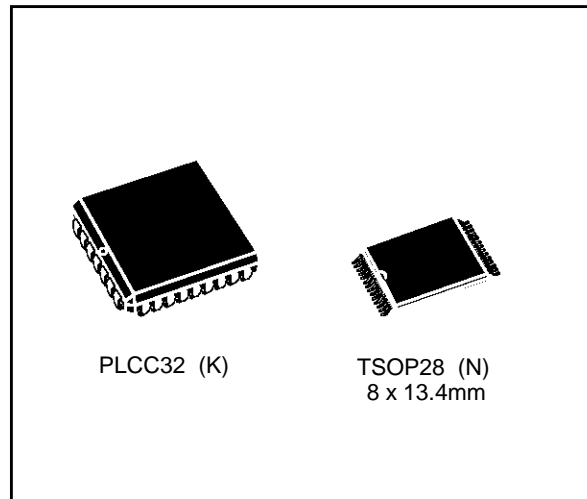
The M27V512 is a low voltage, low power 512K One Time Programmable ROM ideally suited for handheld and portable microprocessor systems requiring large programs. It is organized as 65,536 by 8 bits.

The M27V512 operates in the read mode with a supply voltage as low as 3V. The decrease in operating power allows either a reduction of the size of the battery or an increase in the time between battery recharges. The M27V512 can also be operated as a standard 512K EPROM (similar to M27C512) with a 5V power supply.

For equipment requiring a surface mounted, low profile package, the M27V512 is offered in Plastic Leaded Chip Carrier and Plastic Thin Small Outline packages.

**Table 1. Signal Names**

A0 - A15	Address Inputs
Q0 - Q7	Data Outputs
$\bar{E}$	Chip Enable
$\bar{G}V_{PP}$	Output Enable / Program Supply
V <sub>CC</sub>	Supply Voltage
V <sub>SS</sub>	Ground



**Figure 1. Logic Diagram**

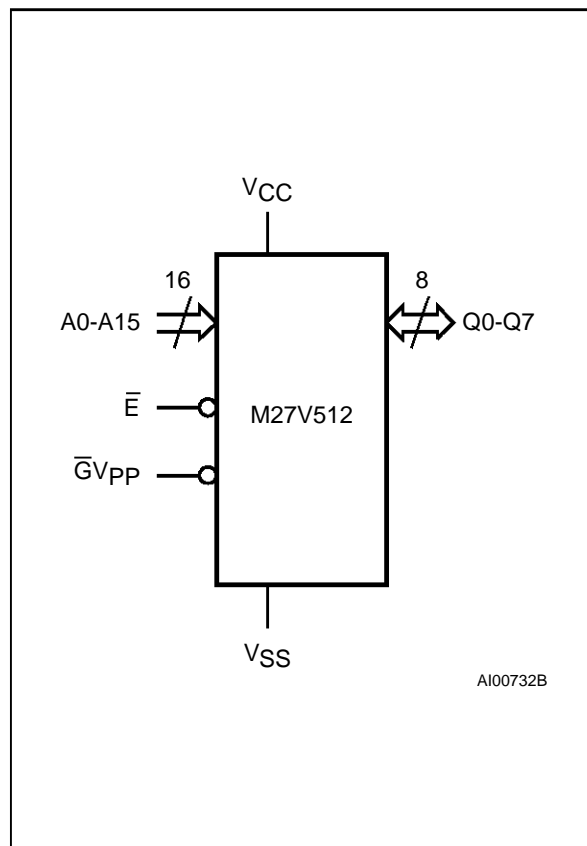
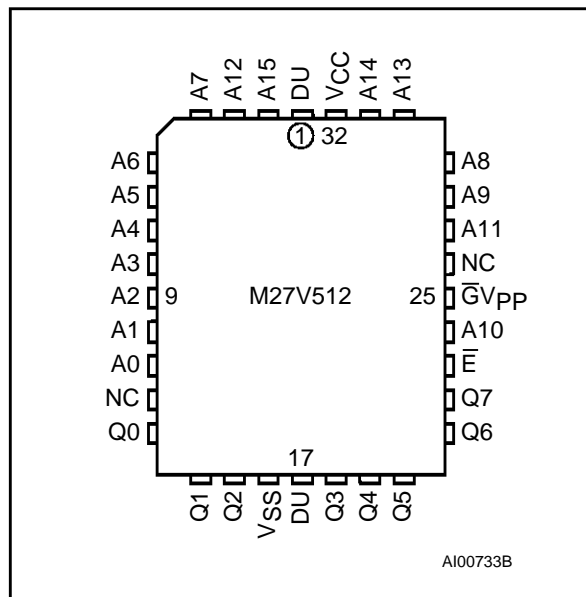


Figure 2A. LCC Pin Connections



Warning: NC = Not Connected, DU = Don't Use.

Figure 2B. TSOP Pin Connections

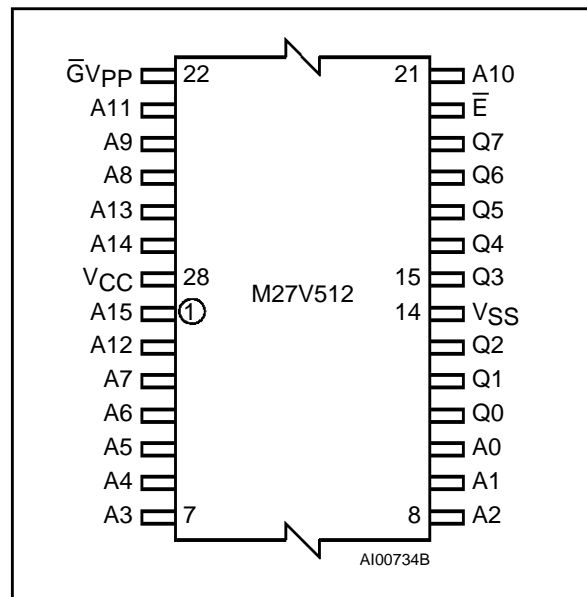


Table 2. Absolute Maximum Ratings <sup>(1)</sup>

Symbol	Parameter	Value	Unit
T <sub>A</sub>	Ambient Operating Temperature	-40 to 125	°C
T <sub>BIAS</sub>	Temperature Under Bias	-50 to 125	°C
T <sub>STG</sub>	Storage Temperature	-65 to 150	°C
V <sub>IO (2)</sub>	Input or Output Voltages (except A9)	-2 to 7	V
V <sub>CC</sub>	Supply Voltage	-2 to 7	V
V <sub>A9 (2)</sub>	A9 Voltage	-2 to 13.5	V
V <sub>PP</sub>	Program Supply Voltage	-2 to 14	V

**Notes:** 1. Except for the rating "Operating Temperature Range", stresses above those listed in the Table "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the Operating sections of this specification is not implied. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability. Refer also to the SGS-THOMSON SURE Program and other relevant quality documents.  
 2. Minimum DC voltage on Input or Output is -0.5V with possible undershoot to -2.0V for a period less than 20ns. Maximum DC voltage on Output is V<sub>CC</sub> +0.5V with possible overshoot to V<sub>CC</sub> +2V for a period less than 20ns.

**DEVICE OPERATION**

The modes of operations of the M27V512 are listed in the Operating Modes table. A single power supply is required in the read mode. All inputs are TTL levels except for GV<sub>PP</sub> and 12V on A9 for Electronic Signature.

**Read Mode**

The M27V512 has two control functions, both of which must be logically active in order to obtain data at the outputs. Chip Enable ( $\bar{E}$ ) is the power control and should be used for device selection. Output Enable ( $\bar{G}$ ) is the output control and should be used to gate data to the output pins, inde-

**DEVICE OPERATION (Cont'd)**

pendent of device selection. Assuming that the addresses are stable, the address access time ( $t_{AVQV}$ ) is equal to the delay from  $\bar{E}$  to output ( $t_{ELQV}$ ). Data is available at the output after a delay of  $t_{GLQV}$  from the falling edge of  $\bar{G}$ , assuming that  $\bar{E}$  has been low and the addresses have been stable for at least  $t_{AVQV} - t_{GLQV}$ .

**Standby Mode**

The M27V512 has a standby mode which reduces the active current from 10mA to 10 $\mu$ A with low voltage operation  $V_{CC} \leq 3.2V$  (30mA to 100 $\mu$ A with a supply of 5.5V), see Read Mode DC Characteristics Table for details. The M27V512 is placed in the standby mode by applying a CMOS high signal to the  $\bar{E}$  input. When in the standby mode, the outputs are in a high impedance state, independent of the  $\bar{G}V_{PP}$  input.

**Two Line Output Control**

Because OTPROMs are often used in larger memory arrays, the product features a 2 line control function which accommodates the use of multiple memory connection. The two line control function allows:

- the lowest possible memory power dissipation,
- complete assurance that output bus contention will not occur.

For the most efficient use of these two control lines,  $\bar{E}$  should be decoded and used as the primary

device selecting function, while  $\bar{G}$  should be made a common connection to all devices in the array and connected to the READ line from the system control bus. This ensures that all deselected memory devices are in their low power standby mode and that the output pins are only active when data is required from a particular memory device.

**System Considerations**

The power switching characteristics of Advanced CMOS OTP ROMs require careful decoupling of the devices. The supply current,  $I_{CC}$ , has three segments that are of interest to the system designer: the standby current level, the active current level, and transient current peaks that are produced by the falling and rising edges of  $\bar{E}$ . The magnitude of the transient current peaks is dependent on the capacitive and inductive loading of the device at the output. The associated transient voltage peaks can be suppressed by complying with the two line output control and by properly selected decoupling capacitors. It is recommended that a 0.1 $\mu$ F ceramic capacitor be used on every device between  $V_{CC}$  and  $V_{SS}$ . This should be a high frequency capacitor of low inherent inductance and should be placed as close to the device as possible. In addition, a 4.7 $\mu$ F bulk electrolytic capacitor should be used between  $V_{CC}$  and  $V_{SS}$  for every eight devices. The bulk capacitor should be located near the power supply connection point. The purpose of the bulk capacitor is to overcome the voltage drop caused by the inductive effects of PCB traces.

**Table 3. Operating Modes**

Mode	$\bar{E}$	$\bar{G}V_{PP}$	A9	Q0 - Q7
Read	$V_{IL}$	$V_{IL}$	X	Data Out
Output Disable	$V_{IL}$	$V_{IH}$	X	Hi-Z
Program	$V_{IL}$ Pulse	$V_{PP}$	X	Data In
Program Inhibit	$V_{IH}$	$V_{PP}$	X	Hi-Z
Standby	$V_{IH}$	X	X	Hi-Z
Electronic Signature	$V_{IL}$	$V_{IL}$	$V_{ID}$	Codes

Note: X =  $V_{IH}$  or  $V_{IL}$ ,  $V_{ID} = 12V \pm 0.5V$

**Table 4. Electronic Signature**

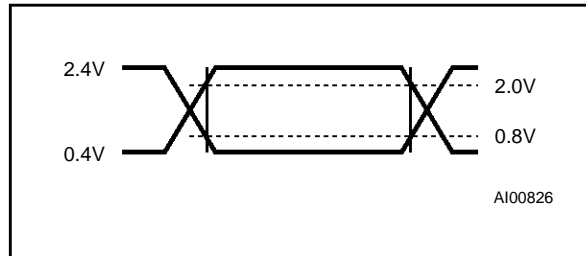
Identifier	A0	Q7	Q6	Q5	Q4	Q3	Q2	Q1	Q0	Hex Data
Manufacturer's Code	$V_{IL}$	0	0	1	0	0	0	0	0	20h
Device Code	$V_{IH}$	0	0	1	1	1	1	0	1	3Dh

**AC MEASUREMENT CONDITIONS**

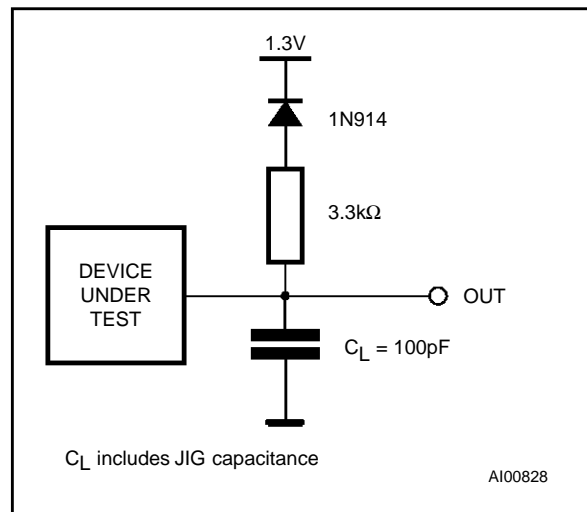
Input Rise and Fall Times  $\leq 20\text{ns}$   
 Input Pulse Voltages 0.4 to 2.4V  
 Input and Output Timing Ref. Voltages 0.8 to 2.0V

Note that Output Hi-Z is defined as the point where data is no longer driven.

**Figure 3. AC Testing Input Output Waveforms**



**Figure 4. AC Testing Load Circuit**



**Table 5. Capacitance<sup>(1)</sup>** ( $T_A = 25\text{ }^\circ\text{C}$ ,  $f = 1\text{ MHz}$ )

Symbol	Parameter	Test Condition	Min	Max	Unit
$C_{IN}$	Input Capacitance	$V_{IN} = 0V$		6	pF
$C_{OUT}$	Output Capacitance	$V_{OUT} = 0V$		12	pF

Note: 1. Sampled only, not 100% tested.

**Table 6. Read Mode DC Characteristics<sup>(1)</sup>**

( $T_A = 0\text{ to }70\text{ }^\circ\text{C}$  or  $-40\text{ to }85\text{ }^\circ\text{C}$ ;  $V_{CC} = 3V\text{ to }5.5V$  unless specified;  $V_{PP} = V_{CC}$ )

Symbol	Parameter	Test Condition	Min	Max	Unit
$I_{LI}$	Input Leakage Current	$0V \leq V_{IN} \leq V_{CC}$		$\pm 10$	$\mu\text{A}$
$I_{LO}$	Output Leakage Current	$0V \leq V_{OUT} \leq V_{CC}$		$\pm 10$	$\mu\text{A}$
$I_{CC}$	Supply Current	$\bar{E} = V_{IL}, \bar{G} = V_{IL}, I_{OUT} = 0\text{mA}, f = 5\text{MHz}, V_{CC} \leq 3.2V$		10	mA
		$\bar{E} = V_{IL}, \bar{G} = V_{IL}, I_{OUT} = 0\text{mA}, f = 5\text{MHz}, V_{CC} = 5.5V$		30	mA
$I_{CC1}$	Supply Current (Standby) TTL	$\bar{E} = V_{IH}$		1	mA
$I_{CC2}$	Supply Current (Standby) CMOS	$\bar{E} > V_{CC} - 0.2V, V_{CC} \leq 3.2V$		10	$\mu\text{A}$
		$\bar{E} > V_{CC} - 0.2V, V_{CC} = 5.5V$		100	$\mu\text{A}$
$I_{PP}$	Program Current	$V_{PP} = V_{CC}$		10	$\mu\text{A}$
$V_{IL}$	Input Low Voltage		-0.3	0.8	V
$V_{IH}^{(2)}$	Input High Voltage		2	$V_{CC} + 1$	V
$V_{OL}$	Output Low Voltage	$I_{OL} = 2.1\text{mA}$		0.4	V
$V_{OH}$	Output High Voltage TTL	$I_{OH} = -400\mu\text{A}$	2.4		V
	Output High Voltage CMOS	$I_{OH} = -100\mu\text{A}$	$V_{CC} - 0.7V$		V

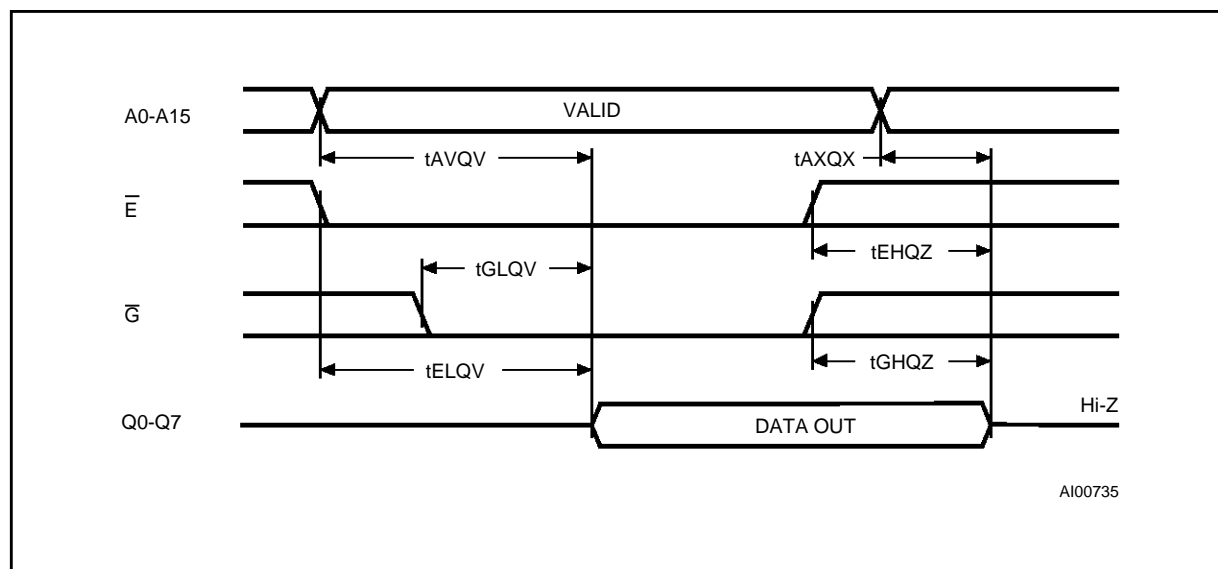
Notes: 1.  $V_{CC}$  must be applied simultaneously with or before  $V_{PP}$  and removed simultaneously or after  $V_{PP}$ .  
 2. Maximum DC voltage on Output is  $V_{CC} + 0.5V$ .

**Table 7. Read Mode AC Characteristics<sup>(1)</sup>**(T<sub>A</sub> = 0 to 70 °C or -40 to 85 °C; V<sub>CC</sub> = 3V to 5.5V unless specified; V<sub>PP</sub> = V<sub>CC</sub>)

Symbol	Alt	Parameter	Test Condition	M27V512						Unit
				-120		-150		-200		
				Min	Max	Min	Max	Min	Max	
t <sub>AVQV</sub>	t <sub>ACC</sub>	Address Valid to Output Valid	$\bar{E} = V_{IL}, \bar{G} = V_{IL}$		120		150		200	ns
t <sub>ELQV</sub>	t <sub>CE</sub>	Chip Enable Low to Output Valid	$\bar{G} = V_{IL}$		120		150		200	ns
t <sub>GLQV</sub>	t <sub>OE</sub>	Output Enable Low to Output Valid	$\bar{E} = V_{IL}$		65		70		80	ns
t <sub>EHQZ</sub> <sup>(2)</sup>	t <sub>DF</sub>	Chip Enable High to Output Hi-Z	$\bar{G} = V_{IL}$	0	60	0	60	0	60	ns
t <sub>GHQZ</sub> <sup>(2)</sup>	t <sub>DF</sub>	Output Enable High to Output Hi-Z	$\bar{E} = V_{IL}$	0	60	0	60	0	60	ns
t <sub>AXQX</sub>	t <sub>OH</sub>	Address Transition to Output Transition	$\bar{E} = V_{IL}, \bar{G} = V_{IL}$	0		0		0		ns

**Notes:** 1. V<sub>CC</sub> must be applied simultaneously with or before V<sub>PP</sub> and removed simultaneously or after V<sub>PP</sub>.

2. Sampled only, not 100% tested.

**Figure 5. Read Mode AC Waveforms**

**Table 8. Programming Mode DC Characteristics <sup>(1)</sup>**(T<sub>A</sub> = 25 °C; V<sub>CC</sub> = 6.25V ± 0.25V; V<sub>PP</sub> = 12.75V ± 0.25V)

Symbol	Parameter	Test Condition	Min	Max	Unit
I <sub>LI</sub>	Input Leakage Current	V <sub>IL</sub> ≤ V <sub>IN</sub> ≤ V <sub>IH</sub>		±10	μA
I <sub>CC</sub>	Supply Current			50	mA
I <sub>PP</sub>	Program Current	$\bar{E} = V_{IL}$		50	mA
V <sub>IL</sub>	Input Low Voltage		-0.3	0.8	V
V <sub>IH</sub>	Input High Voltage		2	V <sub>CC</sub> + 0.5	V
V <sub>OL</sub>	Output Low Voltage	I <sub>OL</sub> = 2.1mA		0.4	V
V <sub>OH</sub>	Output High Voltage TTL	I <sub>OH</sub> = -400μA	2.4		V
V <sub>ID</sub>	A9 Voltage		11.5	12.5	V

**Table 9. MARGIN MODE AC Characteristics <sup>(1)</sup>**(T<sub>A</sub> = 25 °C; V<sub>CC</sub> = 6.25V ± 0.25V; V<sub>PP</sub> = 12.75V ± 0.25V)

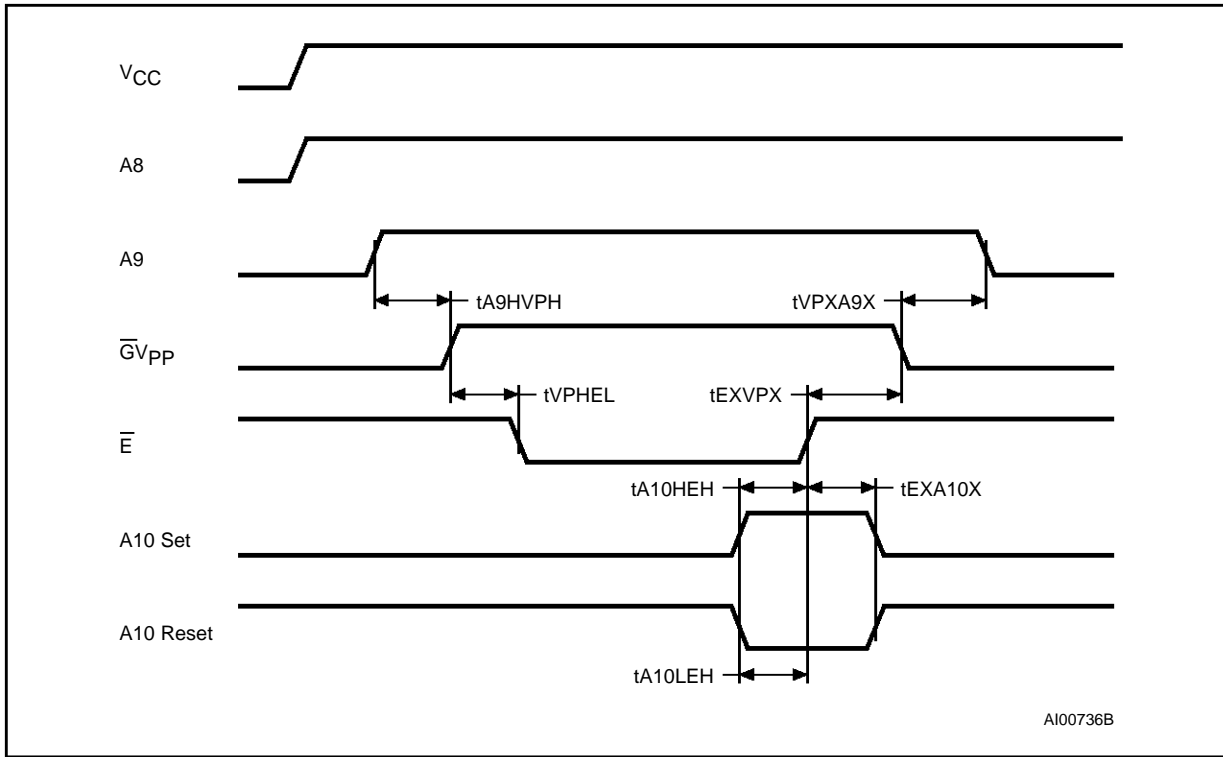
Symbol	Alt	Parameter	Test Condition	Min	Max	Unit
t <sub>A9HVPH</sub>	t <sub>AS9</sub>	VA9 High to V <sub>PP</sub> High		2		μs
t <sub>VPHL</sub>	t <sub>VPS</sub>	V <sub>PP</sub> High to Chip Enable Low		2		μs
t <sub>A10HEH</sub>	t <sub>AS10</sub>	VA10 High to Chip Enable High (Set)		1		μs
t <sub>A10LEH</sub>	t <sub>AS10</sub>	VA10 Low to Chip Enable High (Reset)		1		μs
t <sub>EXA10X</sub>	t <sub>AH10</sub>	Chip Enable Transition to VA10 Transition		1		μs
t <sub>EXVPX</sub>	t <sub>VPH</sub>	Chip Enable Transition to V <sub>PP</sub> Transition		2		μs
t <sub>VXA9X</sub>	t <sub>AH9</sub>	V <sub>PP</sub> Transition to VA9 Transition		2		μs

**Table 10. Programming Mode AC Characteristics <sup>(1)</sup>**(T<sub>A</sub> = 25 °C; V<sub>CC</sub> = 6.25V ± 0.25V; V<sub>PP</sub> = 12.75V ± 0.25V)

Symbol	Alt	Parameter	Test Condition	Min	Max	Units
t <sub>AVEL</sub>	t <sub>AS</sub>	Address Valid to Chip Enable Low		2		μs
t <sub>QVEL</sub>	t <sub>DS</sub>	Input Valid to Chip Enable Low		2		μs
t <sub>VCHL</sub>	t <sub>VCS</sub>	V <sub>CC</sub> High to Chip Enable Low		0		μs
t <sub>VPHL</sub>	t <sub>OES</sub>	V <sub>PP</sub> High to Chip Enable Low		2		μs
t <sub>VPLVPH</sub>	t <sub>PRT</sub>	V <sub>PP</sub> Rise Time		50		ns
t <sub>ELEH</sub>	t <sub>PW</sub>	Chip Enable Program Pulse Width (Initial)		95	105	μs
t <sub>EHQX</sub>	t <sub>DH</sub>	Chip Enable High to Input Transition		2		μs
t <sub>EHVPX</sub>	t <sub>OEH</sub>	Chip Enable High to V <sub>PP</sub> Transition		2		μs
t <sub>VPLEL</sub>	t <sub>VR</sub>	V <sub>PP</sub> Low to Chip Enable Low		2		μs
t <sub>ELQV</sub>	t <sub>DV</sub>	Chip Enable Low to Output Valid			1	μs
t <sub>EHQZ</sub> <sup>(2)</sup>	t <sub>DFFP</sub>	Chip Enable High to Output Hi-Z		0	130	ns
t <sub>EHAX</sub>	t <sub>AH</sub>	Chip Enable High to Address Transition		0		ns

Notes: 1. V<sub>CC</sub> must be applied simultaneously with or before V<sub>PP</sub> and removed simultaneously or after V<sub>PP</sub>.  
 2. Sampled only, not 100% tested.

Figure 6. MARGIN MODE AC Waveforms



Note:  $A_8$  High level = 5V;  $A_9$  High level = 12V.

Figure 7. Programming and Verify Modes AC Waveforms

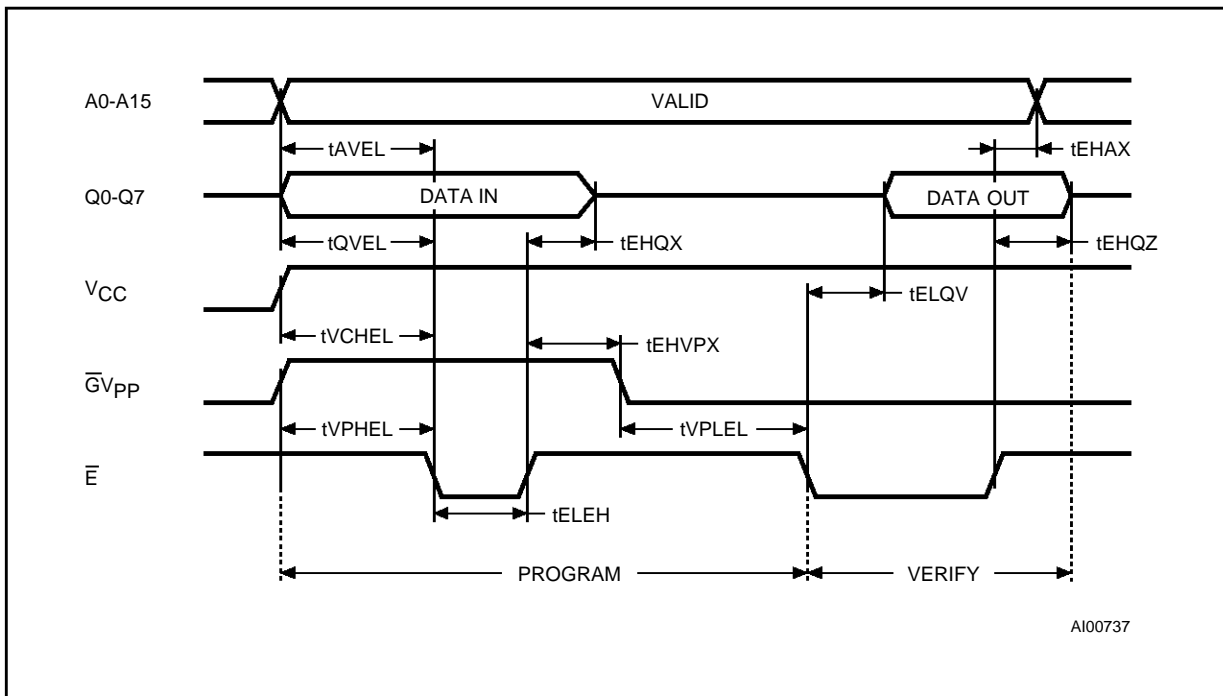
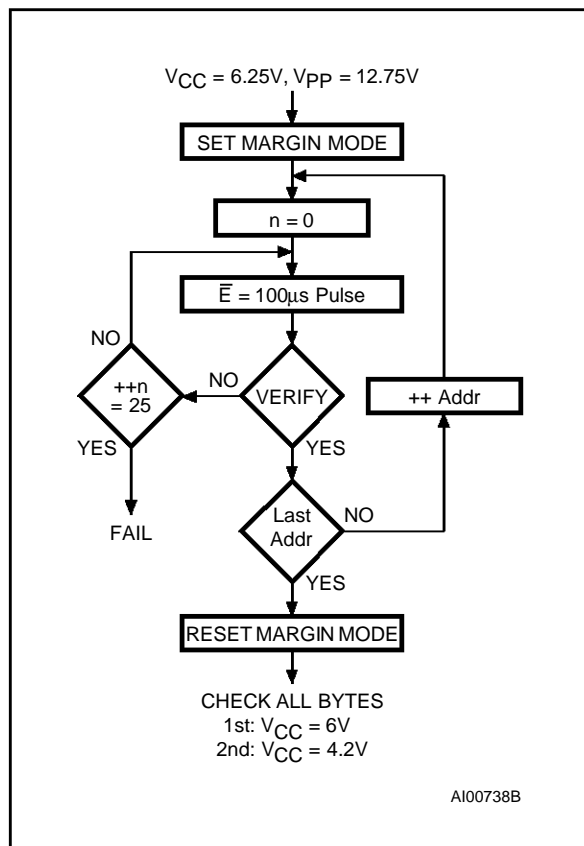


Figure 8. Programming Flowchart



## Programming

The M27V512 has been designed to be fully compatible with the M27C512. As a result the M27V512 can be programmed as the M27C512 on the same programmers applying 12.75V on  $V_{PP}$  and 6.25V on  $V_{CC}$ . The M27V512 has the same electronic signature and uses the same PRESTO IIB algorithm.

When delivered, all bits of the M27V512 are in the "1" state. Data is introduced by selectively programming "0s" into the desired bit locations. Although only "0s" will be programmed, both "1s" and "0s" can be present in the data word. The M27V512 is in the programming mode when  $V_{PP}$  input is at 12.75V and  $\bar{E}$  is at TTL-low. The data to be programmed is applied 8 bits in parallel to the data output pins. The levels required for the address and data inputs are TTL.  $V_{CC}$  is specified to be  $6.25V \pm 0.25V$ .

The M27V512 uses the PRESTO IIB Programming Algorithm that drastically reduces the programming time (typically less than 6 seconds). Nevertheless to achieve compatibility with all programming equipments, PRESTO Programming Algorithm can be used as well.

## PRESTO IIB Programming Algorithm

PRESTO IIB Programming Algorithm allows the whole array to be programmed with a guaranteed margin, a typical time of 6.5 seconds. This can be achieved with SGS-THOMSON M27V512 due to several design innovations to improve programming efficiency and to provide adequate margin for reliability. Before starting the programming the internal MARGIN MODE circuit is set in order to guarantee that each cell is programmed with enough margin. Then a sequence of 100µs program pulses are applied to each byte until a correct verify occurs. No overprogram pulses are applied since the verify in MARGIN MODE provides the necessary margin.

### Program Inhibit

Programming of multiple M27V512s in parallel with different data is also easily accomplished. Except for  $\bar{E}$ , all like inputs including  $\bar{G}V_{PP}$  of the parallel M27V512 may be common. A TTL low level pulse applied to a M27V512's  $\bar{E}$  input, with  $V_{PP}$  at 12.75V, will program that M27V512. A high level  $\bar{E}$  input inhibits the other M27V512s from being programmed.

### Program Verify

A verify (read) should be performed on the programmed bits to determine that they were correctly programmed. The verify is accomplished with  $\bar{G}$  at  $V_{IL}$ . Data should be verified with  $t_{ELQV}$  after the falling edge of  $\bar{E}$ .

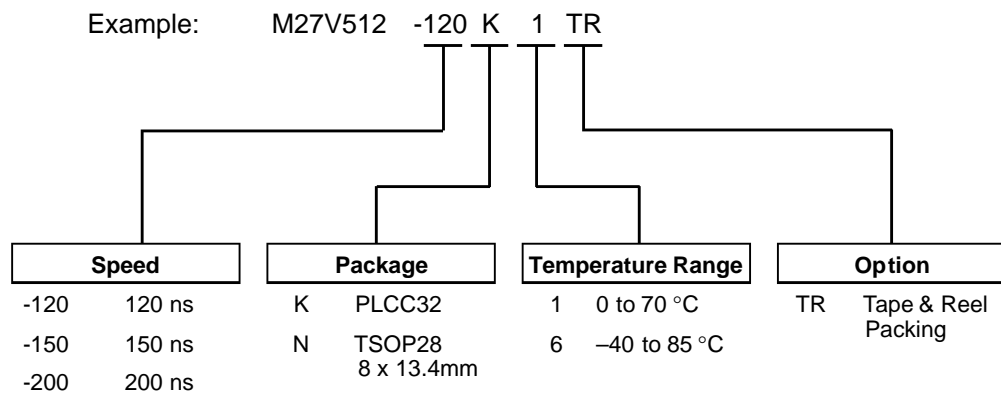
### Electronic Signature

The Electronic Signature mode allows the reading out of a binary code from an EPROM that will identify its manufacturer and type. This mode is intended for use by programming equipment to automatically match the device to be programmed with its corresponding programming algorithm. This mode is functional in the  $25^{\circ}\text{C} \pm 5^{\circ}\text{C}$  ambient temperature range that is required when programming the M27V512. To activate this mode, the programming equipment must apply a Supply Voltage  $V_{CC}$  of 5V and force 11.5V to 12.5V on address line A9 of the M27V512.

Two identifier bytes may then be sequenced from the device outputs by toggling address line A0 from  $V_{IL}$  to  $V_{IH}$ . All other address lines must be held at  $V_{IL}$  during Electronic Signature mode. Byte 0 ( $A0=V_{IL}$ ) represents the manufacturer code and byte 1 ( $A0=V_{IH}$ ) the device identifier code. For the SGS-THOMSON M27V512, these two identifier bytes are given in Table 4 and can be read-out on outputs Q0 to Q7.

Note that the M27V512 and the M27C512 have the same identifier bytes.

## ORDERING INFORMATION SCHEME



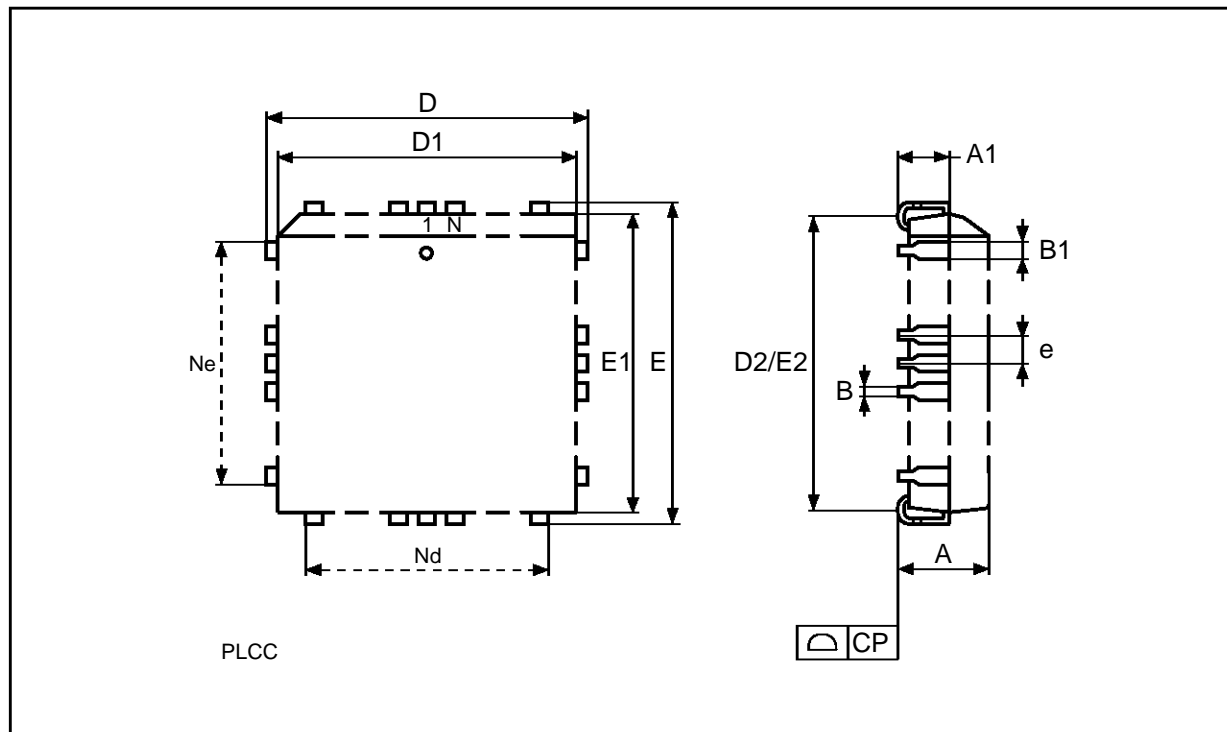
For a list of available options (Speed, Package, Temperature Range, etc...) refer to the current Memory Shortform catalogue.

For further information on any aspect of this device, please contact SGS-THOMSON Sales Office nearest to you.

**PLCC32 - 32 lead Plastic Leaded Chip Carrier, rectangular**

Symb	mm			inches		
	Typ	Min	Max	Typ	Min	Max
A		2.54	3.56		0.100	0.140
A1		1.52	2.41		0.060	0.095
B		0.33	0.53		0.013	0.021
B1		0.66	0.81		0.026	0.032
D		12.32	12.57		0.485	0.495
D1		11.35	11.56		0.447	0.455
D2		9.91	10.92		0.390	0.430
E		14.86	15.11		0.585	0.595
E1		13.89	14.10		0.547	0.555
E2		12.45	13.46		0.490	0.530
e	1.27	-	-	0.050	-	-
N		32			32	
Nd		7			7	
Ne		9			9	
CP			0.10			0.004

PLCC32

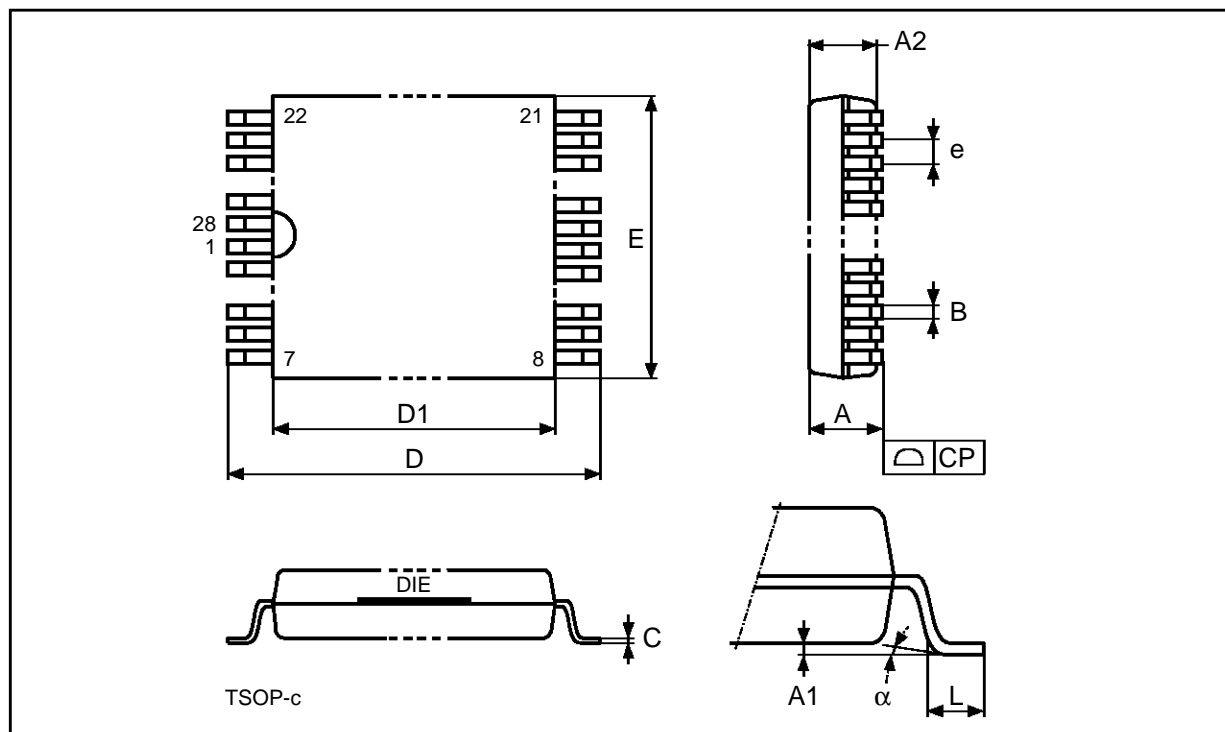


Drawing is not to scale

### TSOP28 - 28 lead Plastic Thin Small Outline, 8 x 13.4mm

Symb	mm			inches		
	Typ	Min	Max	Typ	Min	Max
A			1.25			0.049
A1			0.20			0.008
A2		0.95	1.15		0.037	0.045
B		0.17	0.27		0.007	0.011
C		0.10	0.21		0.004	0.008
D		13.20	13.60		0.520	0.535
D1		11.70	11.90		0.461	0.469
E		7.90	8.10		0.311	0.319
e	0.55	–	–	0.022	–	–
L		0.50	0.70		0.020	0.028
$\alpha$		0°	5°		0°	5°
N	28			28		
CP			0.10			0.004

TSOP28



Drawing is not to scale

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