

AN3826NK

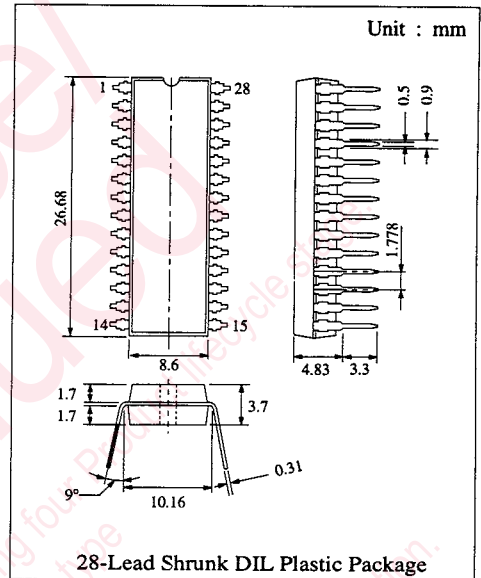
VCR Capstan Motor Driver

■ Description

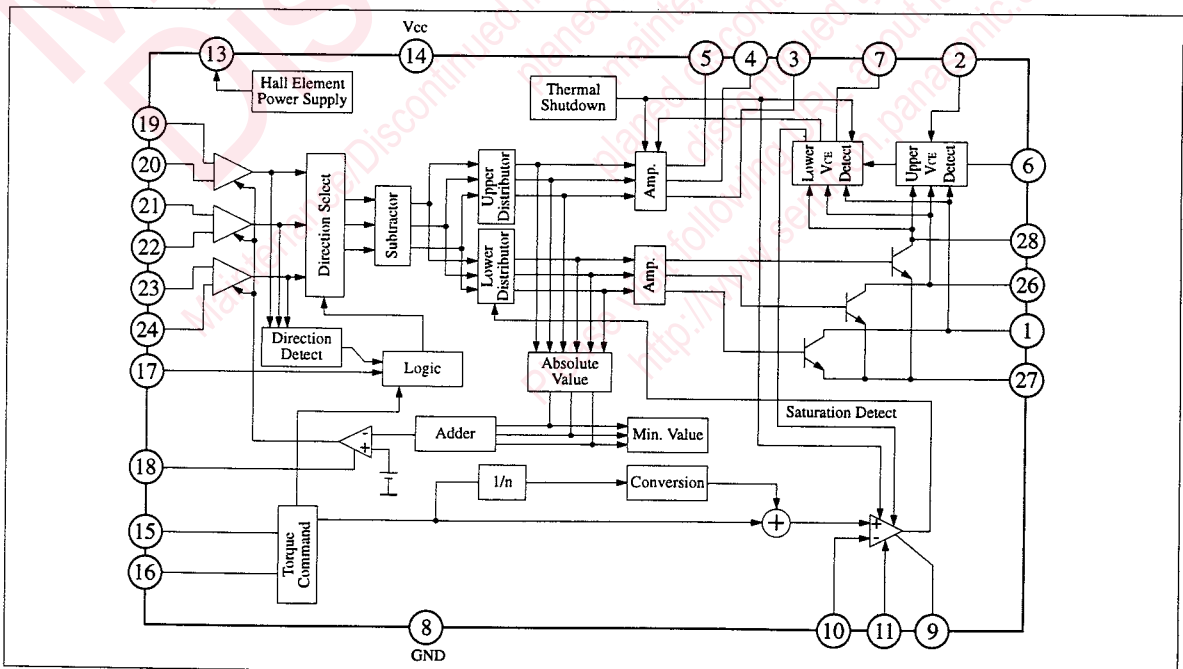
The AN3826NK is an integrated circuit designed as VCR capstan Hall motor drives.

■ Features

- Operating supply voltage range : $V_{cc}=4.5V$ to $5.5V$
- 3-phase full-wave 180° power-on, overlap drive
- Max. motor voltage : $V_M=20V$
- Max. output current $I_{omax}=1A$
- Built-in torque ripple cancellation circuit
- Built-in Hall amplifier and AGC circuit



■ Block Diagram



■ Pin Descriptions

Pin No.	Pin Name	Typ. Waveform	Description	I/O Impedance	Equivalent Circuit
2	VM motor power		Input the motor power		
3 4 5	MP3 upper predrive output 3 MP2 upper predrive output 2 MP1 upper predrive output 1		Predrive output of the output transistor on the source side (upper)		
6	VS switching power control output		Output a voltage proportional to VCE of the output transistor on the source side in order to control the switching power	14.5kΩ	
7	PCV voltage feedback system phase compensation.		Phase compensation pin for the control system of the output transistor on the source side		
8	GND		Ground pin		
9	PCI current feedback system phase compensation		Phase compensation pin for the current control system of the output transistor on the sync. side		
10	CS current detection		Connect to the ATC pin. Input a current value detected by a resistor		
11	TL torque limit		Sets the max. voltage of the ATC pin		
13	VH+ Hall element power supply		Output the supply voltage for Hall elements		

■ Absolute Maximum Ratings (Ta=25°C)

Item	Symbol	Rating	Unit	Note
Supply Voltage	V _{cc}	6	V	
Motor Supply Voltage	V ₂	20	V	
Motor Drive Current	I _n	±1.5	A	n = 26, 28, 9
Output Pin Voltage	V _n	20	V	n = 26, 28, 9
Pin Voltage	V _m	V _{cc}	V	m = 6, 10, 11, 15, 16, 17, 19, 20, 21, 22, 23, 24
Pin 13 Current	I ₁₃	-100	mA	
Power Dissipation (Ta=70°C)	P _D	1790	mW	
Operating Ambient Temperature	Topr	-20 ~ +70	°C	
Storage Temperature	Tstg	-55 ~ +150	°C	

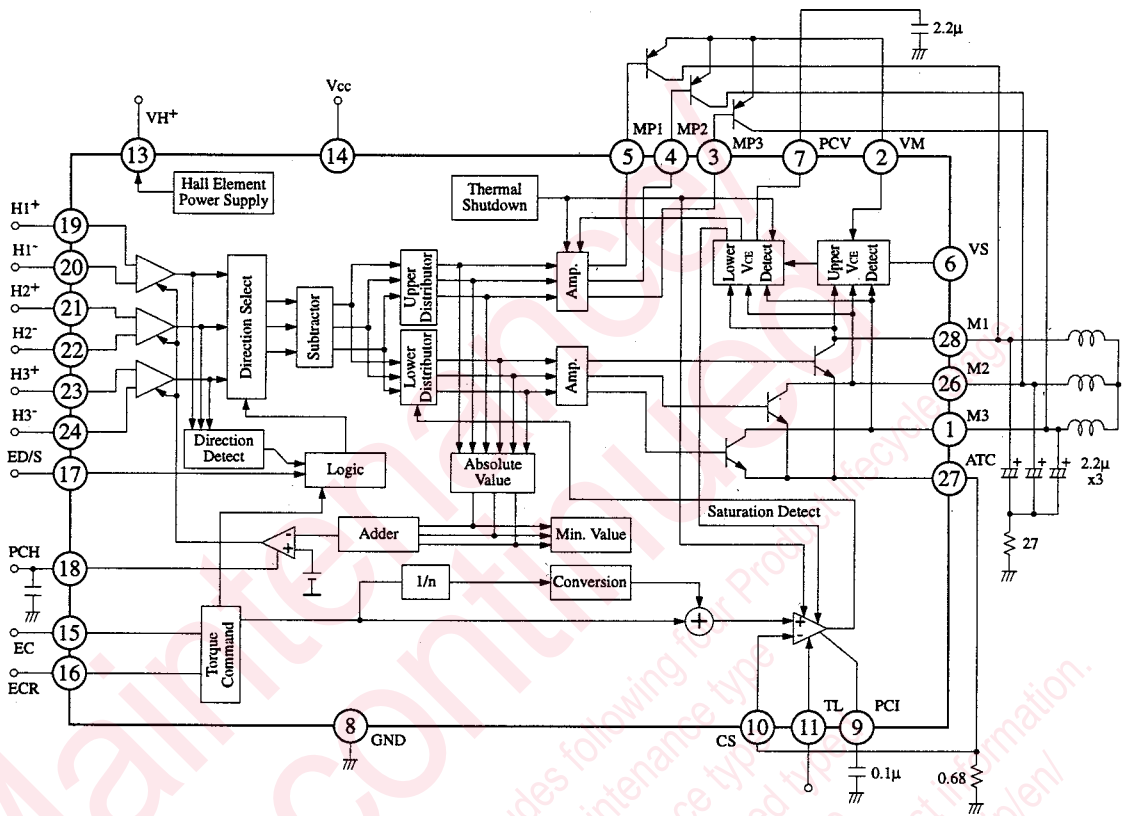
■ Recommended Operating Range (Ta=25°C)

Item	Symbol	Range
Operating Supply Voltage Range	V _{cc}	4.5V ~ 5.5V

■ Electrical Characteristics (V_{cc}=5V, Ta=25°C)

Item	Symbol	Condition	min.	typ.	max.	Unit
Supply current	I _{cc}	Hall element supply current excluded			15	mA
Torque command ref. voltage	ECR		2		3.5	V
Torque command voltage	EC		0.5		4	V
Torque command input offset voltage	EC _{offset}		-150		150	mV
Torque command dead zone	EC _{DZ}		40		130	mV
Output idle voltage	ATC _{idle}				4	mV
I/O gain	G _{io}		0.59	0.65	0.71	times
Maximum output voltage	ATC _{max}		0.75			V
Forward command voltage	ED _F				0.9	V
Stop command voltage	ED _S		1.3		3	V
Reverse command voltage	ED _R		3.5			V
Hall element input allowable voltage	H _{in}		1.2		4	V
Hall element input offset voltage	H _{offset}		-8		8	mV
Lower output voltage (1)	V _{N(1)}	ATC = 68mV	0.37		0.61	V
Lower output voltage (2)	V _{N(2)}	ECR = 2.5V, EC = 0.5V			3.2	V
TL-CS offset voltage	TL _{offset}	TL = 600mV,	10		45	mV
Ripple cancellation rate	a	ECR-EC = 0.2V	4		18	%
Upper drive max. current	IMP		15			mA
Hall element supply voltage	V _{H+}	I _{VH+} = 20mA	2.6	2.85	3.2	V
Switching power control output	V _S	V _{M-M1} = 1V	1.5		3	V
Switching power control output gain	G _{VS}		1.5		2.5	times

■ Application Circuit



■ Pin Descriptions (Continue)

Pin No.	Pin Name	Typ. Waveform	Description	I/O Impedance	Equivalent Circuit
14	Vcc		Input the supply voltage		
15	EC torque command input		Input a torque command voltage		
16	ECR torque command ref. input		Input a torque command ref. voltage		
17	ED/S rotary direction command input		Specifies a motor rotary direction and stop with a 3-valued input		
18	PCH Hall amp. phase compensation		AGC loop phase compensation pin for the Hall amplifier		
19 20 21 22 23 24	H1+ Hall element input H1- Hall element input H2+ Hall element input H2- Hall element input H3+ Hall element input H3- Hall element input		Input Hall element output for the motor		
26 28 1	M2 motor coil pin 2 M1 motor coil pin 1 M3 motor coil pin 3		Connect to the motor coil		
27	ATC total current output		Output the total current of output transistors		

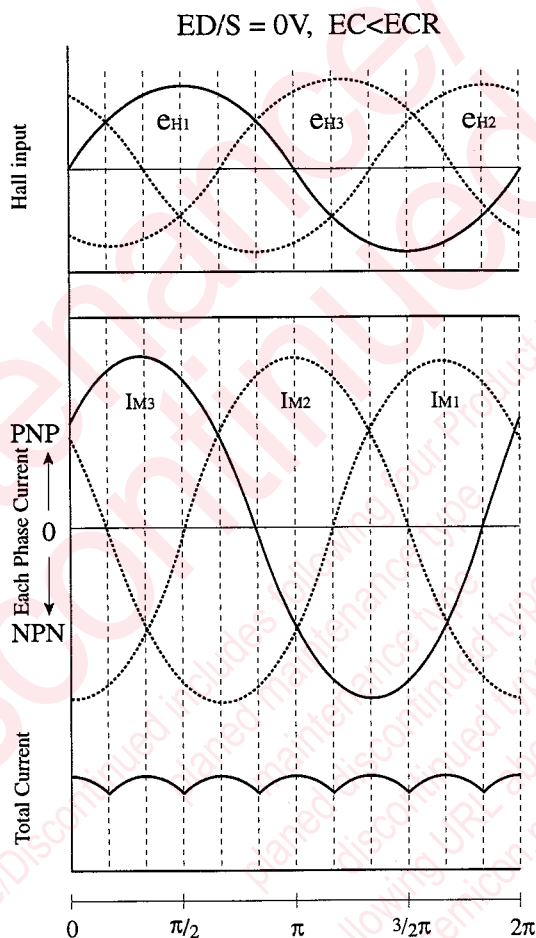
■ Supplementary Explanation

● Electrical Characteristic Design Reference Value ($T_a=25^\circ\text{C}$)

Item	Symbol	Condition	min.	typ.	max.	Unit
Thermal protective circuit operation temperature	T_{ON}		150	175	200	$^\circ\text{C}$

Note) The above characteristic is a design reference value, not a guarantee value.

● Hall Input and Output Current Phases



● Torque Direction Setting Logic

A direction of generated torque is determined by the following information.

- Information from the rotary direction detection : ER
High : $H1 \rightarrow H3 \rightarrow H2$
- Brake information from the torque command circuit : EA
High : $ECR < EC$
- Rotary direction command : ED
High : $H1 \rightarrow H3 \rightarrow H2$
 $H1 \rightarrow H3 \rightarrow H2$ (forward rotation) at $ED/S=0V$

- Direction of generated torque : EP
High : Generates a torque rotating in the direction of $H1 \rightarrow H3 \rightarrow H2$
EP is determined as follows, depending on ER, EA, or ED.

	\overline{EA}	EA		\overline{EA}
ED	H	H	H	L
\overline{ED}	H	L	L	L
	\overline{ER}		ER	

Torque Direction Setting Karnaugh's Diagram

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